



Depth, and Motion in Vision

CMSC 436/636

Penny Rheingans

University of Maryland Baltimore County



Depth Perception

Magnocellular Division

- Discriminates objects from one another
- Characteristics (relative to parvocellular path)
 - color : insensitive to wavelength variations
 - acuity : larger RF centers
 - speed : faster and more transient response
 - contrast : more sensitive to low contrast stimuli
- Observed characteristics of motion perception
 - color-blind: impaired at equiluminance
 - quickness
 - high contrast sensitivity
 - low acuity : impaired at high spatial frequencies

Depth Pathway

- Red and green cones
- Type A retinal ganglion cells
- Magnocellular layers in LGN
- Primary visual cortex
 - disparity tuned neurons (thick stripes in V2)
- Middle Temporal Lobe (MT)

Motor Cues

- Vergence
- Accomodation

Binocular Cues

- Depth cues resulting from two views (one from each eye)
- Include:
 - retinal disparity (stronger for close objects)
 - neurons sensitive to particular disparities

Monocular Cues

- Depth cues available in single eye image
- Include:
 - Occlusion
 - Size
 - Perspective
 - Head-motion parallax
 - Kinetic depth effect (object-motion parallax)

Motion and Interaction



Roles of Motion Processing

- Required for Pattern Vision
- Driving Eye Movements
- Time to Collision
- Exproprioceptive Information
- Perception of Moving Objects
- Depth from Motion
- Encoding 3D Shape
- Image Segmentation



Characteristics of Motion Perception

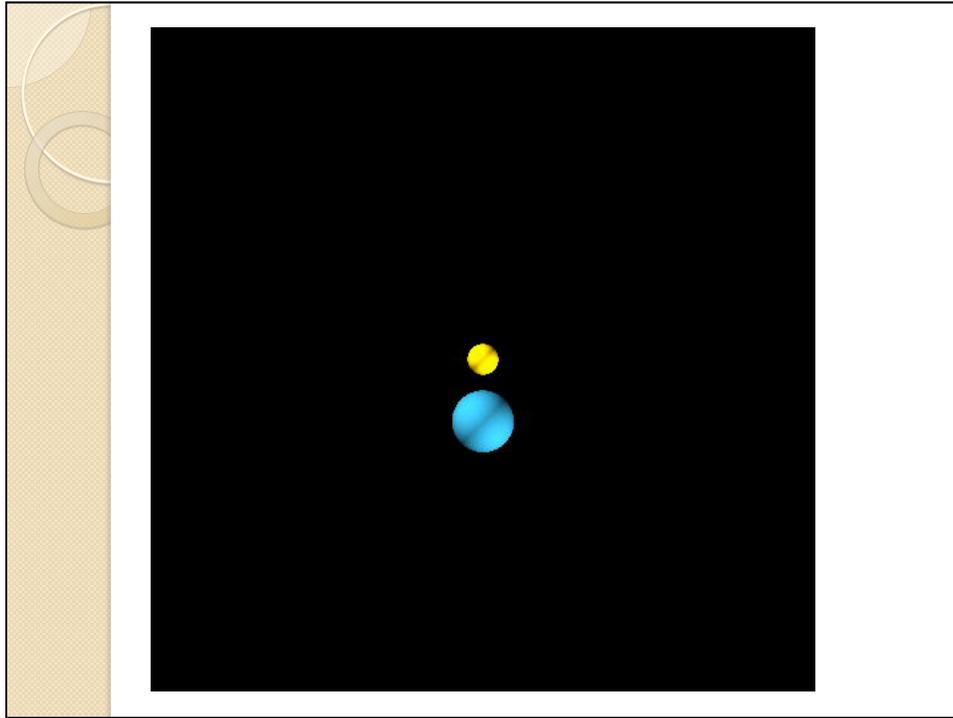
- Fundamental, independent visual process
 - motion aftereffects
 - motion blindness
- Based primarily on brightness
- Ability to interpret structure degrades in periphery
- Spatio-temporal interactions

Motion Pathway

- Red and green cones
- Type A retinal ganglion cells
- Magnocellular layers in LGN
- Area 4B in primary visual cortex
 - direction selectivity
 - velocity selectivity
 - expansion/contraction of visual field
 - global rotation
- Middle temporal lobe

Apparent Motion

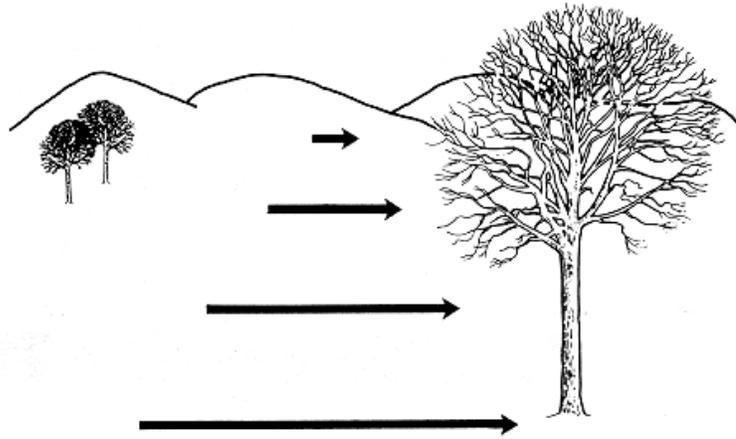
- Def: perception of motion without stimulus continuity (stroboscopic and cine)
- Influences
 - spatial frequency characteristics
 - global field effects
 - number of frames
 - expectations from reality
- Limitations
 - maximum of 300 msec interstimulus interval
 - decreased size constancy (max ~8 Hz)
 - decreased sense of observer motion



Depth from Motion

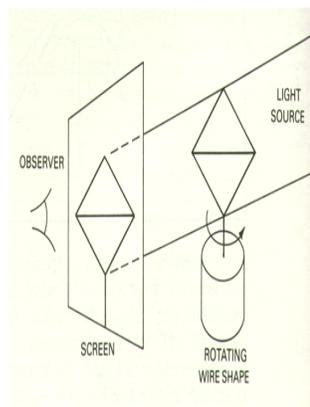
- Motion depth cues
 - head motion parallax
 - kinetic depth effect
 - magnitude of motion indicates relative depth
- Applications
 - indicating relative object positions
 - compensating for lack of other depth cues
- Limits
 - relative, not absolute depth
 - perceived size, perceived depth related

Head Motion Parallax

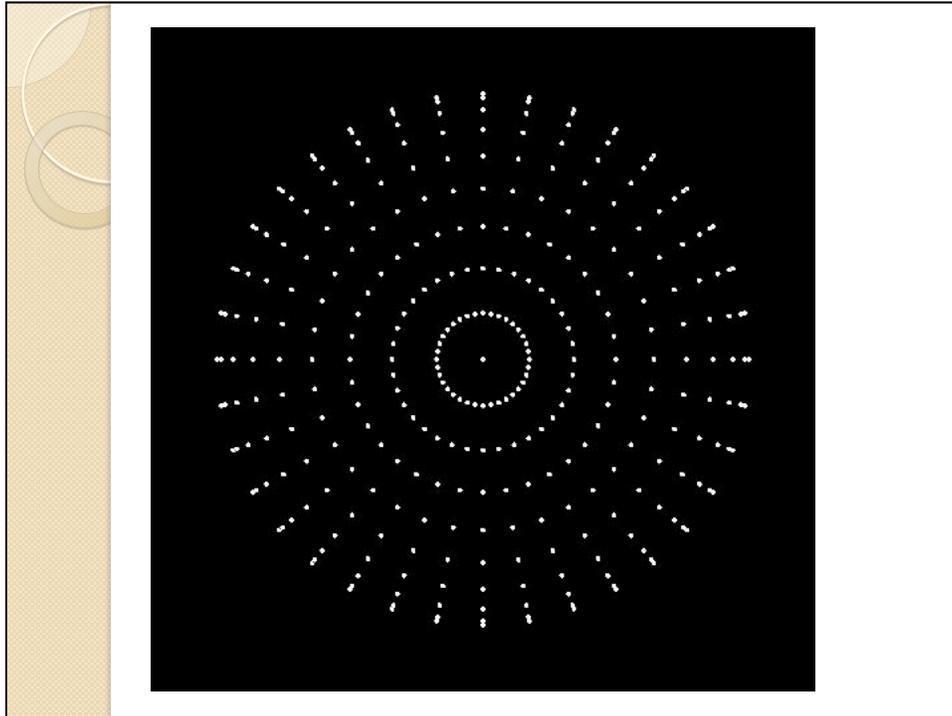


- Bruce and Green '90, p. 231.

Kinetic Depth Effect



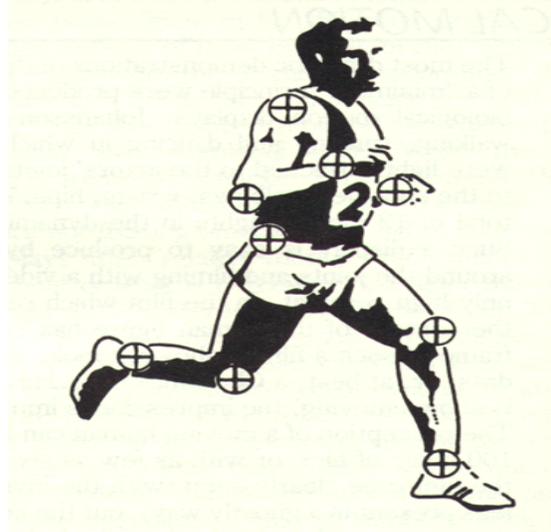
- Bruce and Green '90, pg. 162.



3D Structure from Motion

- Relative motion conveys info about 3D shape
- Rigidity assumption
- Applications
 - understanding of irregular/unfamiliar shapes
 - disambiguation of 2D projections
- Limits
 - 2 frames (large number of structured points)
 - 2-3 points (many frames)
 - 15 arc min (maximum displacement)

Structure from Motion



- Bruce and Green '90, pg. 328.

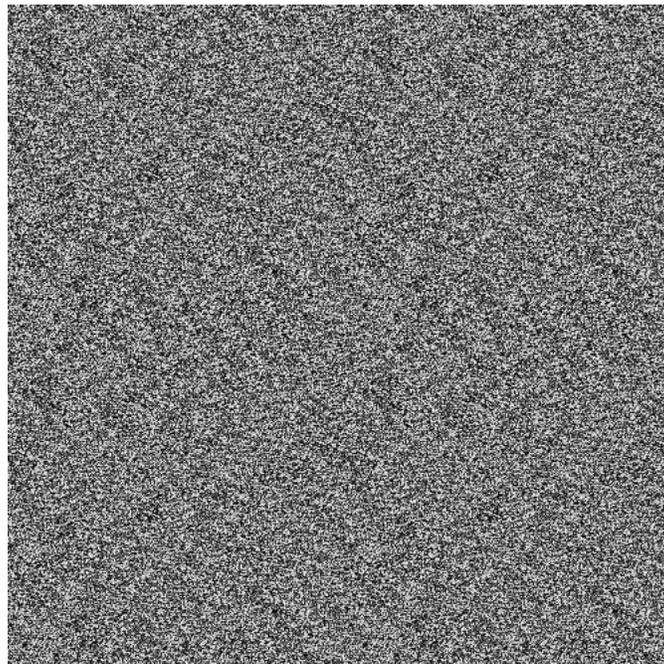


Image Segmentation

- Discontinuities in optical velocity field indicate object boundaries
- Boundaries can be detected on the basis of motion alone
- Applications
 - disambiguation of complex scenes
 - grouping of similar objects

At Equiliminance

- Motion perception of gratings degrades
- Depth perception disappears
- Depth from relative motion disappears
- Shape from relative motion disappears

Interaction vs. Animation

- Exploration vs. Presentation
 - efficiency
 - flexibility
- Active vs. Passive Participation
 - immediacy
 - control
 - development
 - understanding

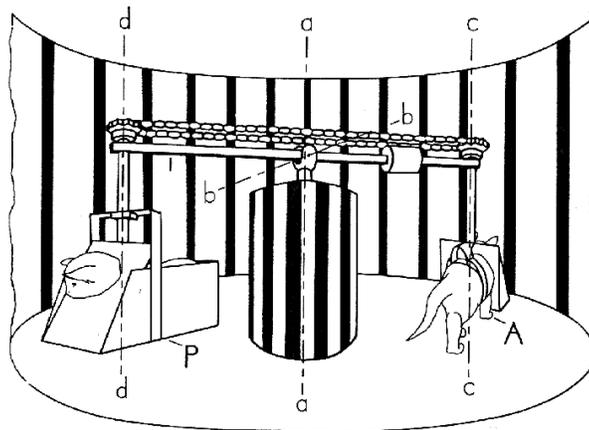
Interactive Control

- Scene
 - viewpoint and direction
 - object position and orientation
- Content
 - variables
 - timestep
- Representation
 - techniques
 - parameters

Experimental Findings

- Control necessary for development
 - Held and Hein '63
- Dynamic control improves shape identification
 - van Damme '94
 - Rheingans '92, '93
- Control improves assembly performance
 - Smets and Overbeeke '95
- Differences between types of control
 - Ware and Francke '96
 - Pausch, Proffitt, Williams '97
 - Ush, et al. '99

Kitten Carousel

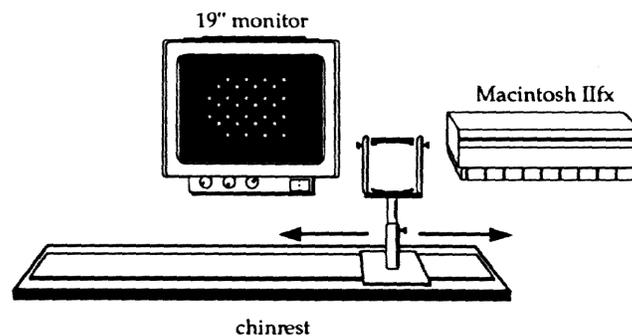


- Held and Hein '63.

Experimental Findings

- Control necessary for development
 - Held and Hein '63
- Dynamic control improves shape identification
 - van Damme '94
 - Rheingans '92, '93
- Control improves assembly performance
 - Smets and Overbeeke '95
- Differences between types of control
 - Ware and Francke '96
 - Pausch, Proffitt, Williams '97
 - Usoh, et al. '99

Shape Identification



- van Damme '94, p. 18.

Effects of Control

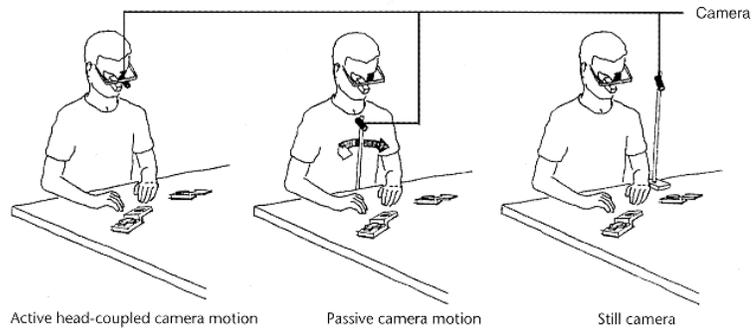
		Control		
		None	Pace	Complete
Change	Jerky	Slide Show	Slide Projector	Interactive
	Smooth	Constant Loop	Multispeed Loop	Dynamic

- Rheingans '92, '93, '97.

Experimental Findings

- Control necessary for development
 - Held and Hein '63
- Dynamic control improves shape identification
 - van Damme '94
 - Rheingans '92, '93
- Control improves assembly performance
 - Smets and Overbeeke '95
- Differences between types of control
 - Ware and Francke '96
 - Pausch, Proffitt, Williams '97
 - Usoh, et al. '99

Assembly Performance

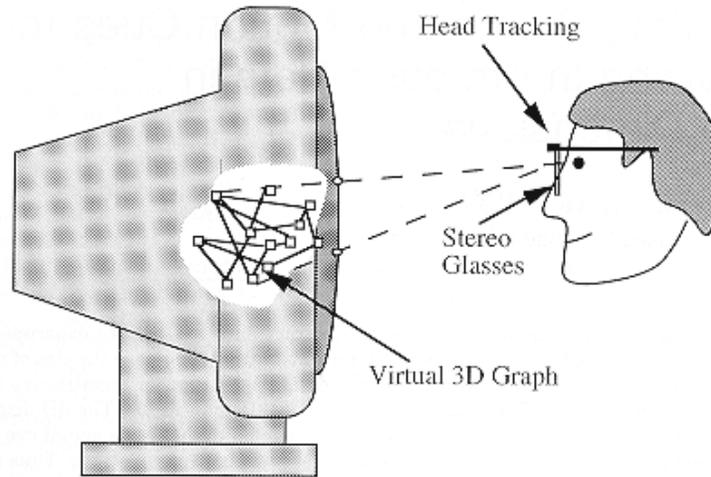


- Smets and Overbeeke '95, p. 47.

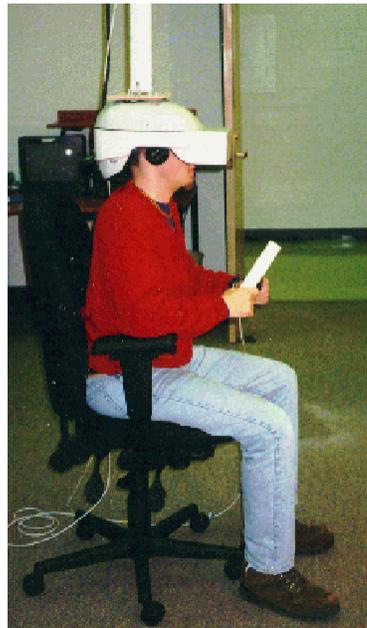
Experimental Findings

- Control necessary for development
 - Held and Hein '63
- Dynamic control improves shape identification
 - van Damme '94
 - Rheingans '92, '93
- Control improves assembly performance
 - Smets and Overbeeke '95
- Differences between types of control
 - Ware and Francke '96
 - Pausch, Proffitt, Williams '97
 - Ush, et al. '99

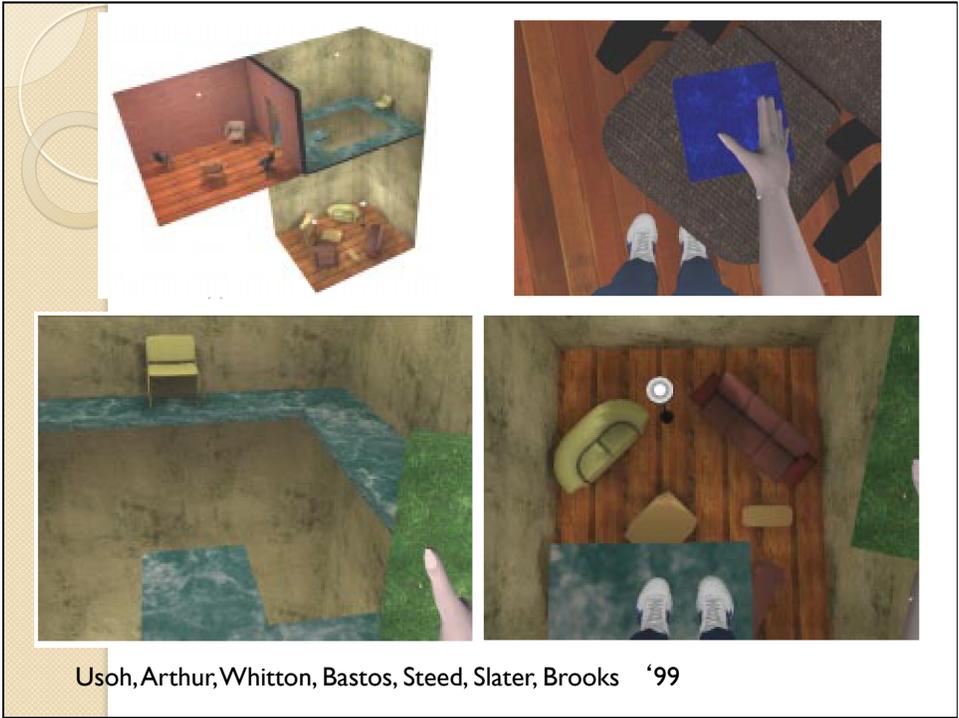
Type of Control



- Ware and Francke '96, p. 122.



Pausch, Proffitt, Williams '97



Usoh, Arthur, Whitton, Bastos, Steed, Slater, Brooks '99