

CMSC 435

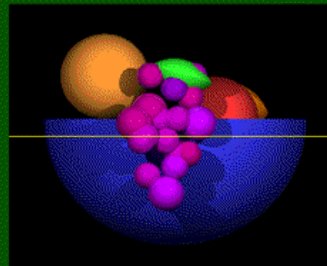
Introductory Computer Graphics

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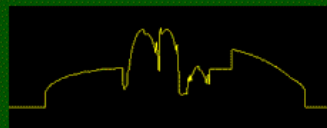
Announcements

Rendering Process

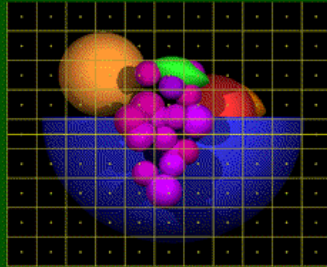
- Two basic stages
 - sampling
 - Reconstruction
- Sampling in rasterization
 - Ray locations in ray tracing
 - Evaluation points in barycentric formulation
 - Implicit evaluation locations in scanline rasterization
- Assuming discrete sampling



**Original
scene**



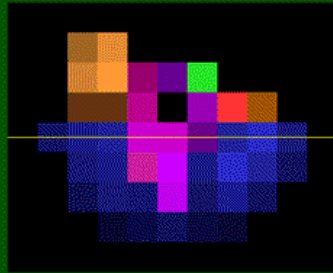
**Luminosity
signal**



**Sampling at
pixel centers**



**Sampled
signal**



**Rendered
image**

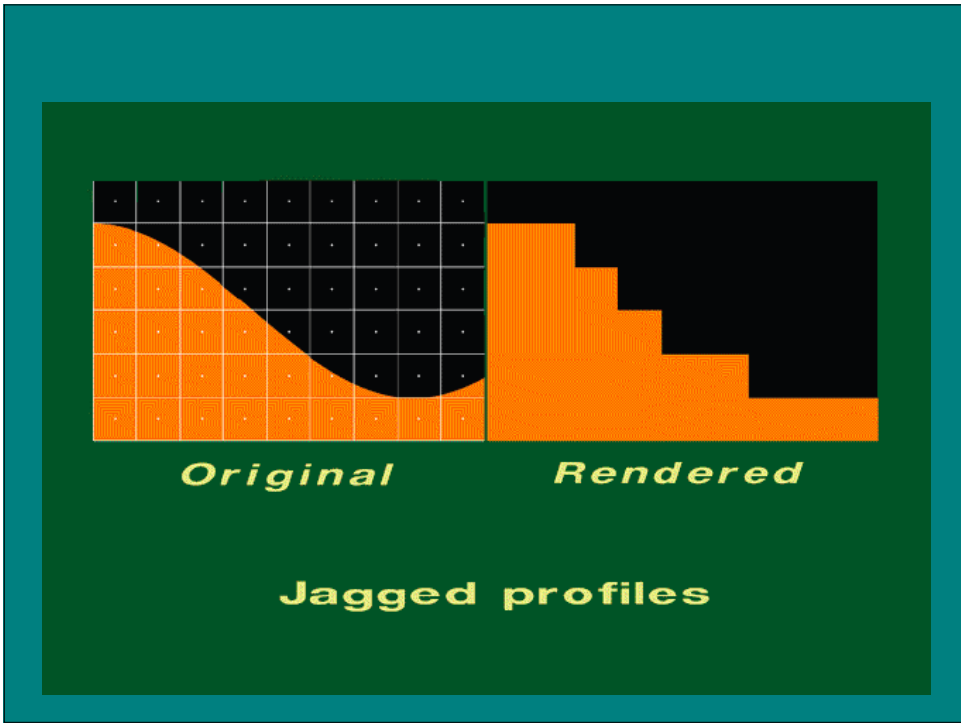
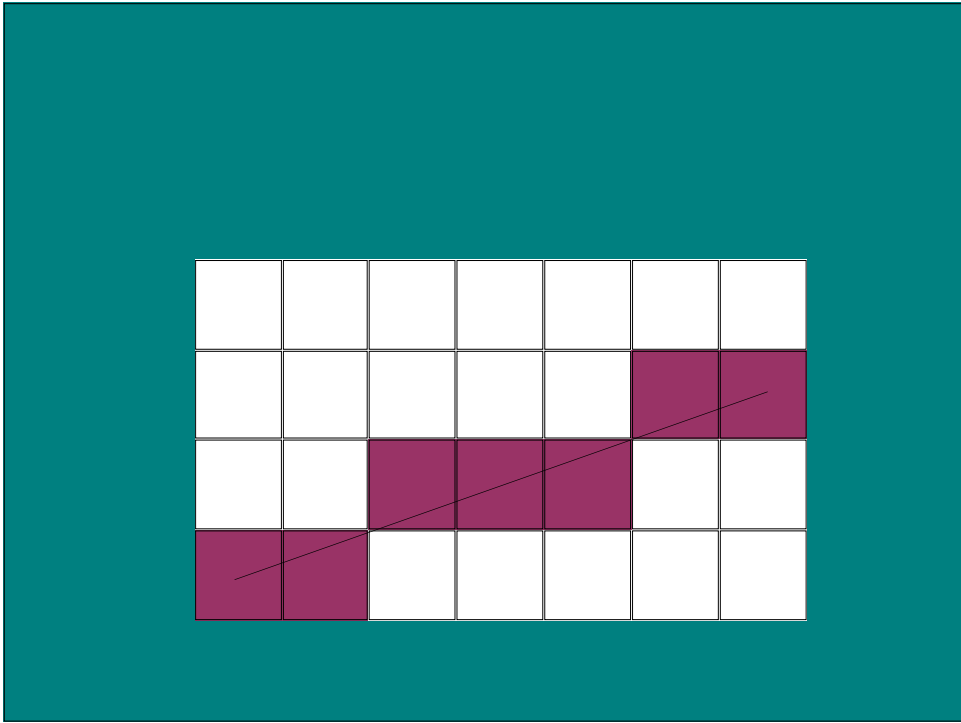


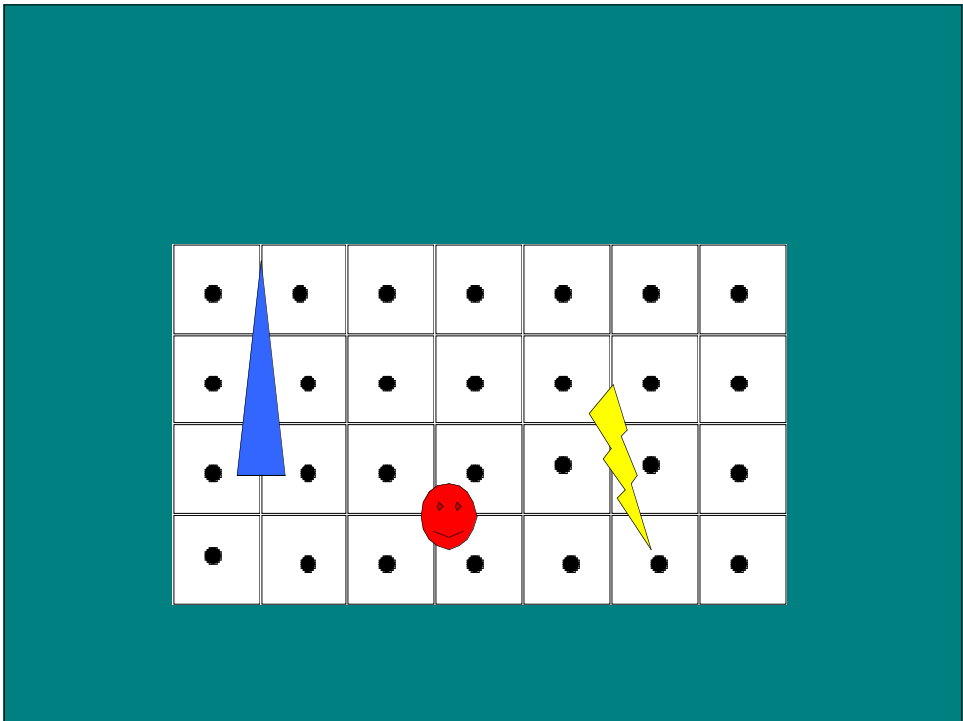
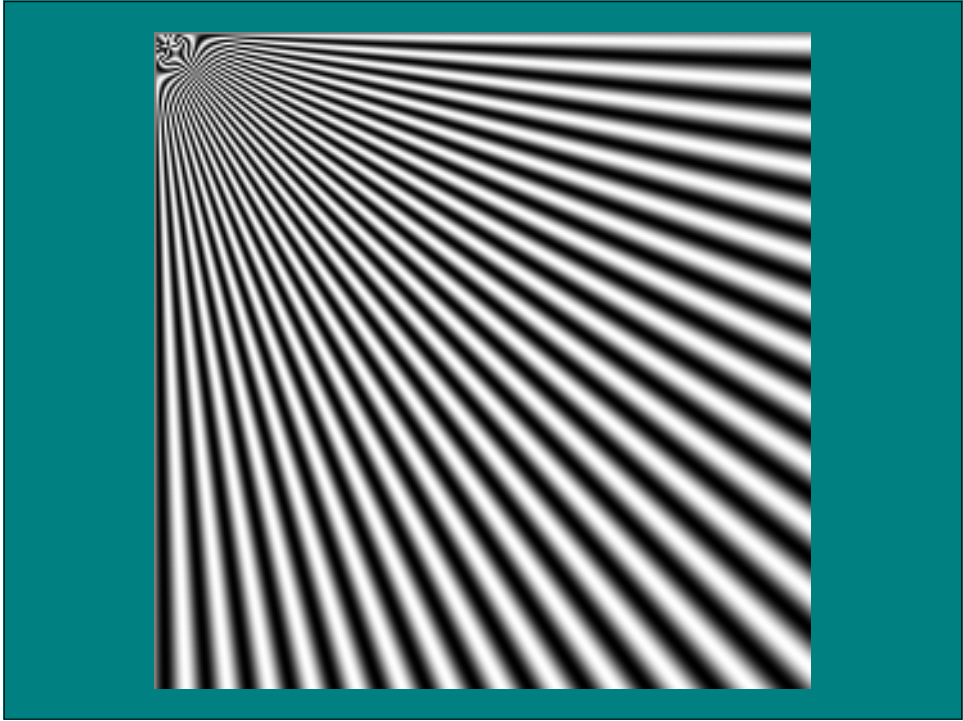
**Luminosity
signal**

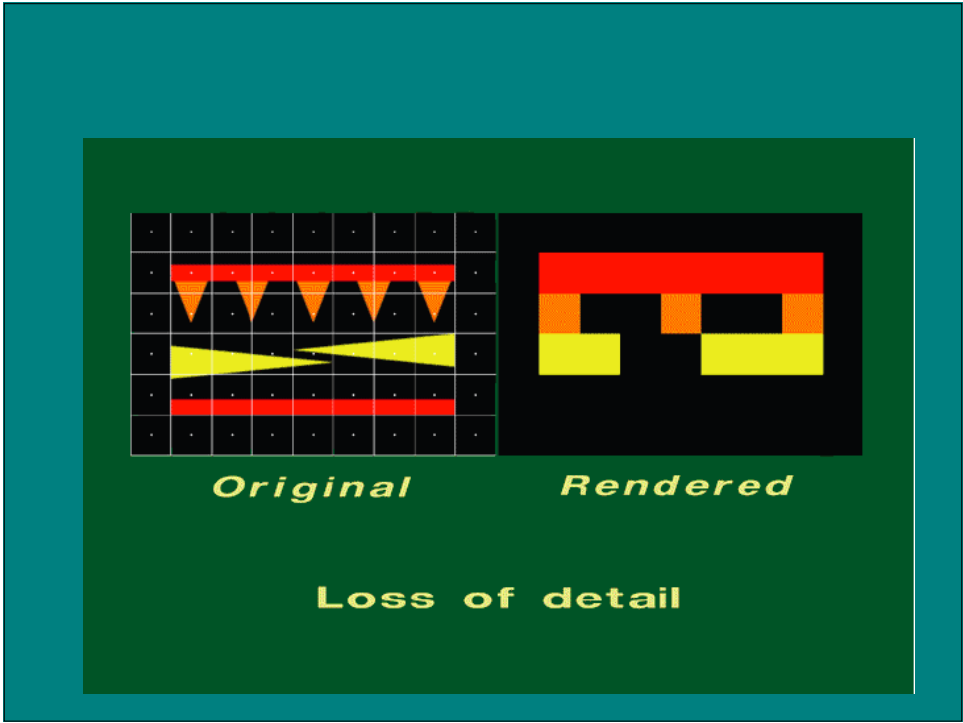
What went wrong?

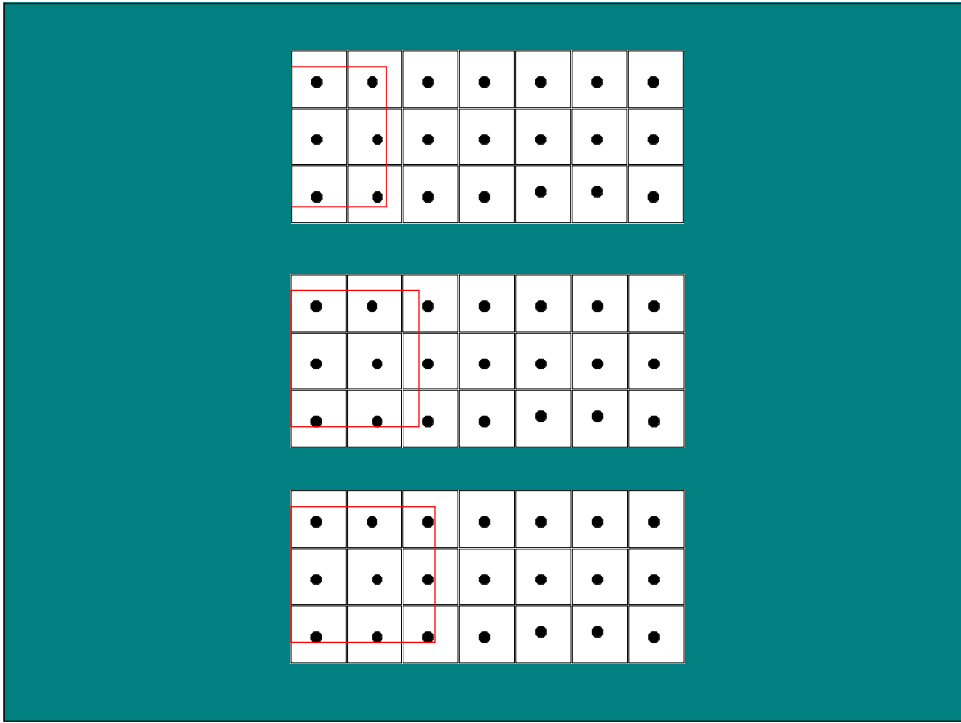
Aliasing

- Visual artifacts
 - jagged lines and edges
 - high frequencies appearing as low
 - small objects missed
 - texture distortions
 - strobing and popping
 - backward movement

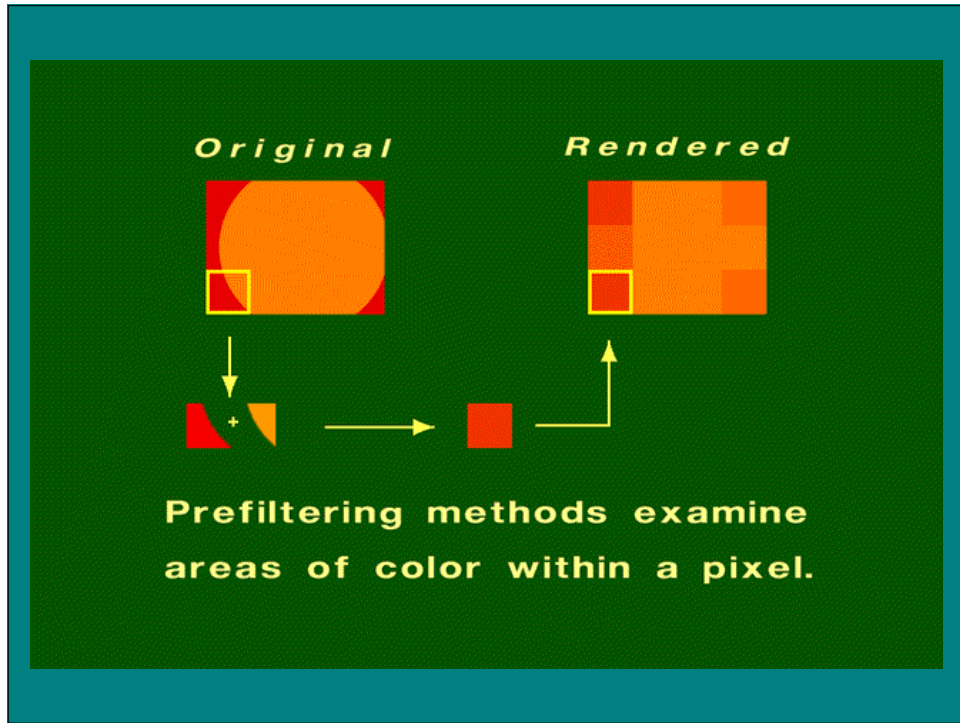








How might you fix aliasing?



Hello World
Hello World

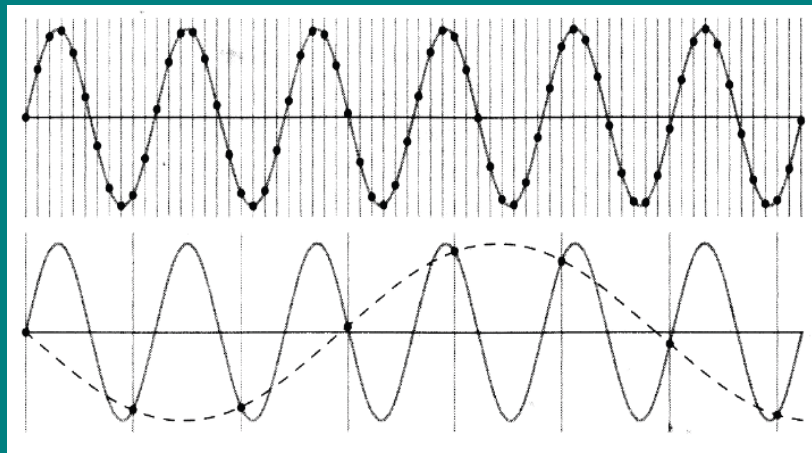
A demonstration



Sampling Theory

- Shannon's sampling theory (1D):
 - A band limited signal $f(t)$ with cut off frequency w_F may be perfectly reconstructed from its samples $f(nT_0)$ if $2\pi/T_0 \geq 2w_F$
 - w_F == Nyquist limit
- Alternatively:
 - a signal can be reconstructed exactly from samples only if the highest frequency is less than half the sampling rate

Sampling a Sine Wave



Convolution

- Operation on two functions that produces another function as the result
- Indicated by *
- Example: Moving average

$$h(x) = \frac{1}{2r} \int_{x-r}^{x+r} g(t) dt$$

$$c[i] = \frac{1}{2r+1} \sum_{j=i-r}^{i+r} b[j]$$

Discrete Convolution

$$(a * b)[i] = \sum_j a[j][b[i-j]]$$

- Finite support: some r such that a[j]=0 whenever |j| >= r
- Alternatively, convolution as sum of shifted filters
 - Filter gives weights

Example: Moving average as convolution with box

$$b[i] = \begin{cases} 1 & : i \geq 0 \\ 0 & : i < 0 \end{cases}$$

$$a[j] = \begin{cases} 1 & : -2 \leq j \leq 2 \\ 0 & : \textit{otherwise} \end{cases}$$

Convolution with continuous filters

$$(f * g)(x) = \int_{-\infty}^{+\infty} f(t)g(x-t)dt$$

- Area under curve of product after shifting

Example: convolution of 2 boxes

$$f(x) = \begin{cases} 1: -1/2 \leq x \leq 1/2 \\ 0: \textit{otherwise} \end{cases}$$

Fourier Transforms

- Basis Functions
 - orthogonal: projection of any onto another is 0
 - complex exponentials as foundations for Fourier Series
- Concepts
 - image space
 - frequency space

Fourier Transforms (cont.)

- Fourier Transform

$$X(\omega) = \frac{1}{\sqrt{2\pi}} \int x(t) e^{-j\omega t} dt$$

- Inverse Fourier Transform

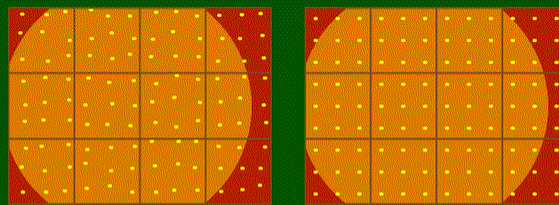
$$x(t) = \frac{1}{\sqrt{2\pi}} \int X(\omega) e^{j\omega t} d\omega$$

Properties of Filters

- Interpolating vs approximating
 - Through sample points vs near
- Degree of continuity
 - Degree of differentiability
- Separable
 - Different dimensions do not interact

Sampling Schemes

- Regular supersampling
- Jittered supersampling
- Adaptive supersampling
- Stochastic sampling



Jittered

Regular

Taking 9 samples per pixel

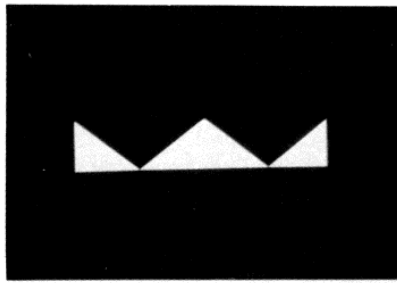
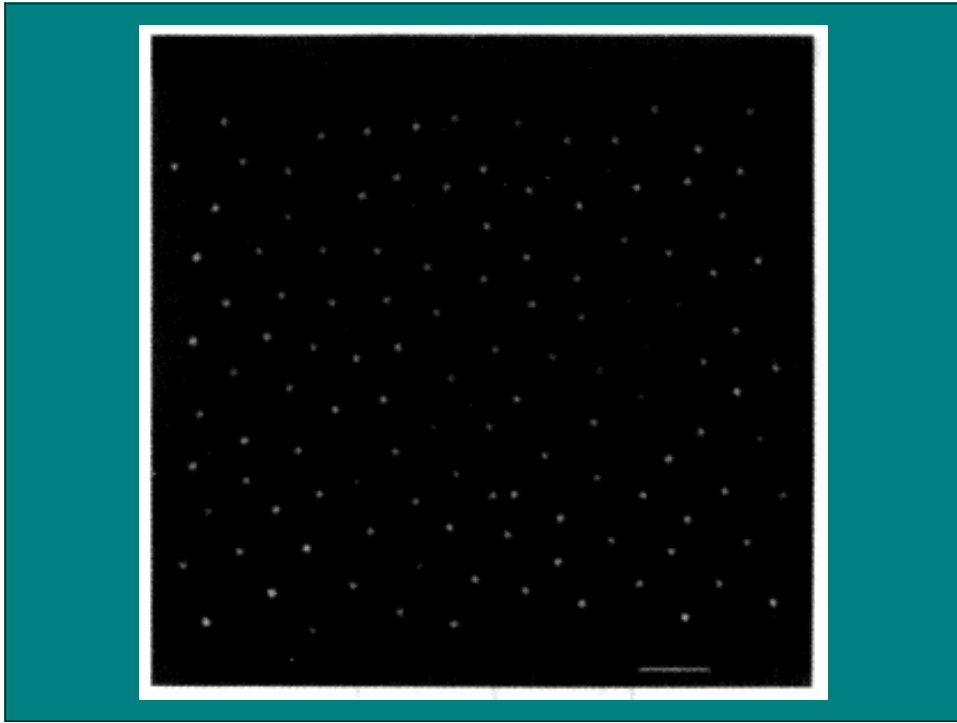


Fig. 12c. Comb rendered with a regular grid, one sample per pixel.

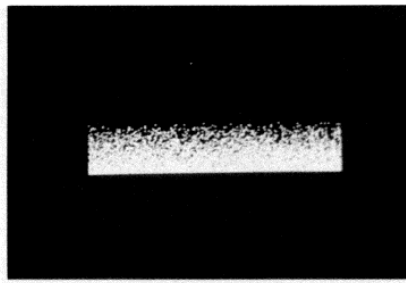
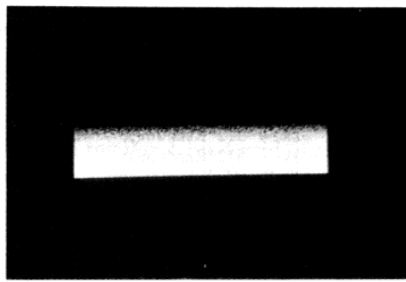
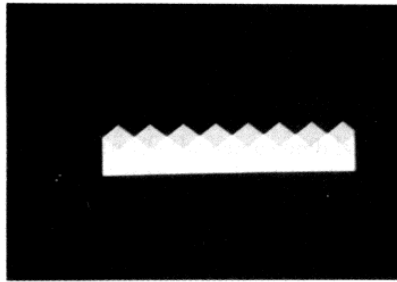
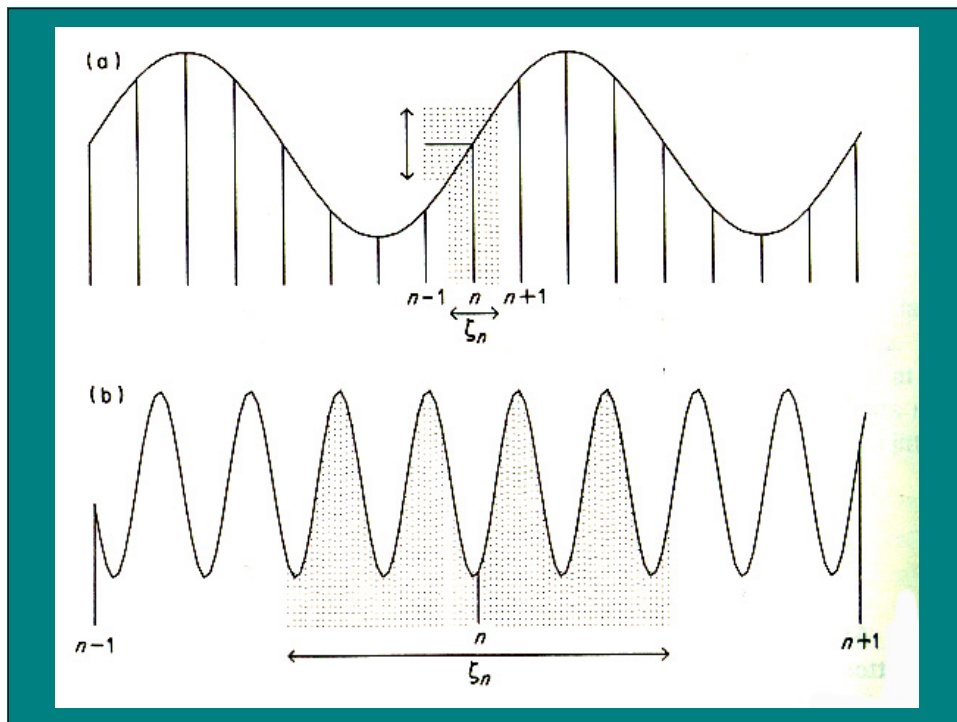


Fig. 12d. Comb rendered with a jittered grid, one sample per pixel.





Reconstruction

- Two basic stages
 - Sampling : continuous to discrete
 - Reconstruction : discrete to continuous
- Tasks of reconstruction filter
 - remove extraneous replicas of signal spectrum
 - pass the original signal base unchanged
- 2D version

$$(a * b)[i, j] = \sum_{i'} \sum_{j'} a[i', j'] b[i - i', j - j']$$

$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$
$\frac{1}{8}$	$\frac{1}{4}$	$\frac{1}{8}$
$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$

*Combines
nine
samples*

**Filters combine samples
to find a pixel's color.**

$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$	$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$
$\frac{1}{8}$	$\frac{1}{4}$	$\frac{1}{8}$	$\frac{1}{8}$	$\frac{1}{4}$	$\frac{1}{8}$
$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$	$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$
$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$	$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$
$\frac{1}{8}$	$\frac{1}{4}$	$\frac{1}{8}$	$\frac{1}{8}$	$\frac{1}{4}$	$\frac{1}{8}$
$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$	$\frac{1}{16}$	$\frac{1}{8}$	$\frac{1}{16}$

**This filter
computes
a weighted
average.**



Samples

Pixels

No antialiasing



**3x3 supersampling
3x3 unweighted filter**

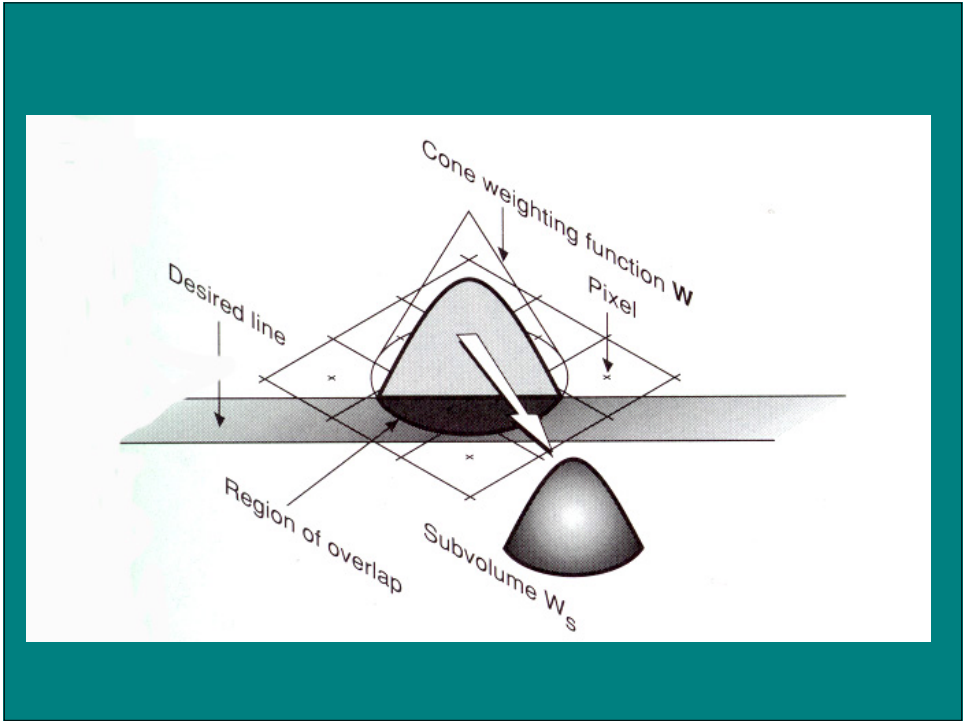
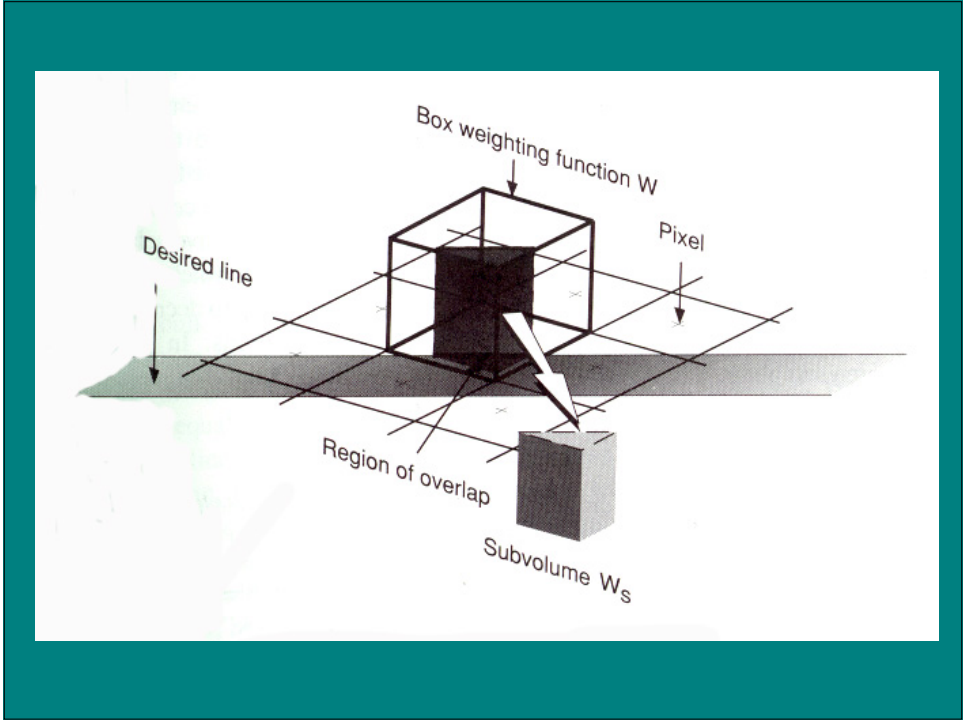


**3x3 supersampling
5x5 weighted filter**

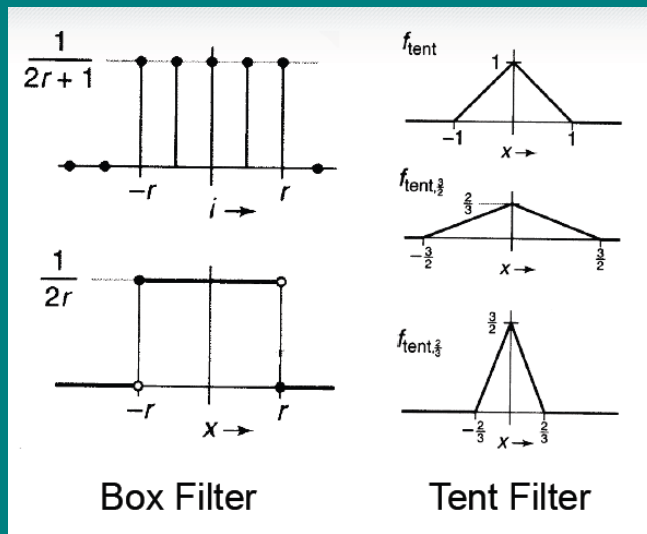


**3x3 jittered supersampling
5x5 weighted filter**





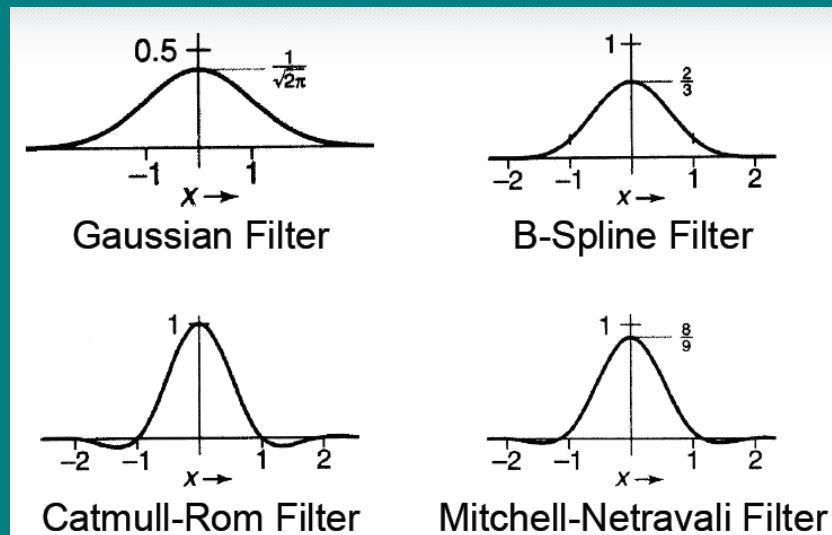
Convolution Filters



Box Filter

Tent Filter

Convolution Filters



Gaussian Filter

B-Spline Filter

Catmull-Rom Filter

Mitchell-Netravali Filter

Reconstruction Artifacts

- Aliasing
 - prealiasing: from undersampling
 - postaliasing: from poor reconstruction
- Blurring
- Ringing
- Sample-frequency ripple
- Anisotropic effects

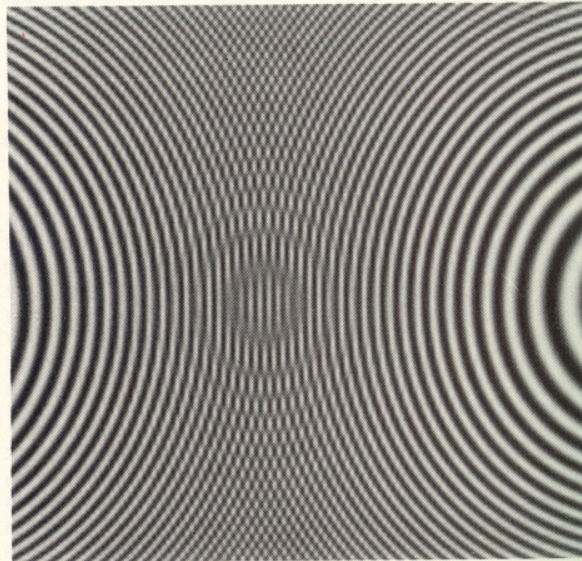


Figure 4. Prealiasing and Postaliasing Example

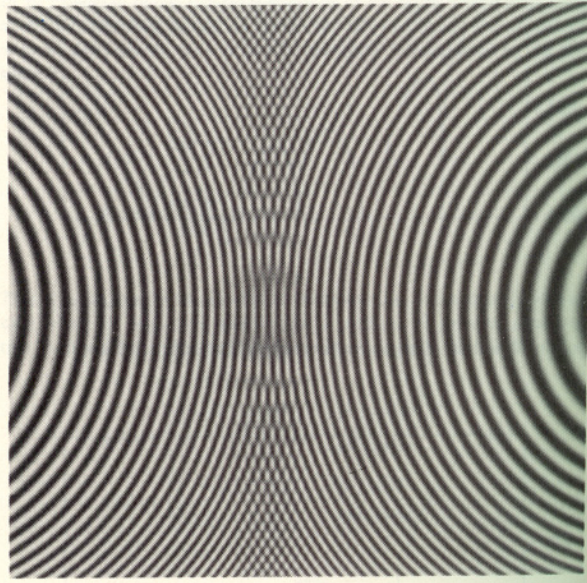


Figure 5. Nearly Ideal Postfiltering

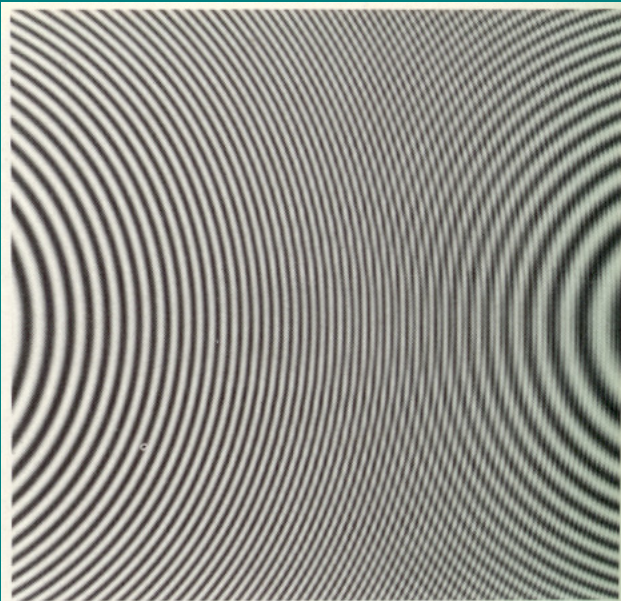


Figure 15. Using Derivative Reconstruction



Figure 11. Excessive Blurring

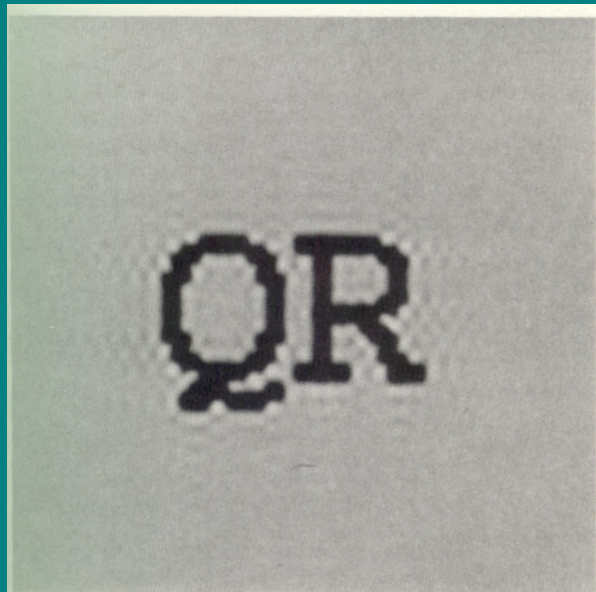


Figure 6. Ringing Caused By Sinc Postfilter



Figure 8. Sample-Frequency Ripple



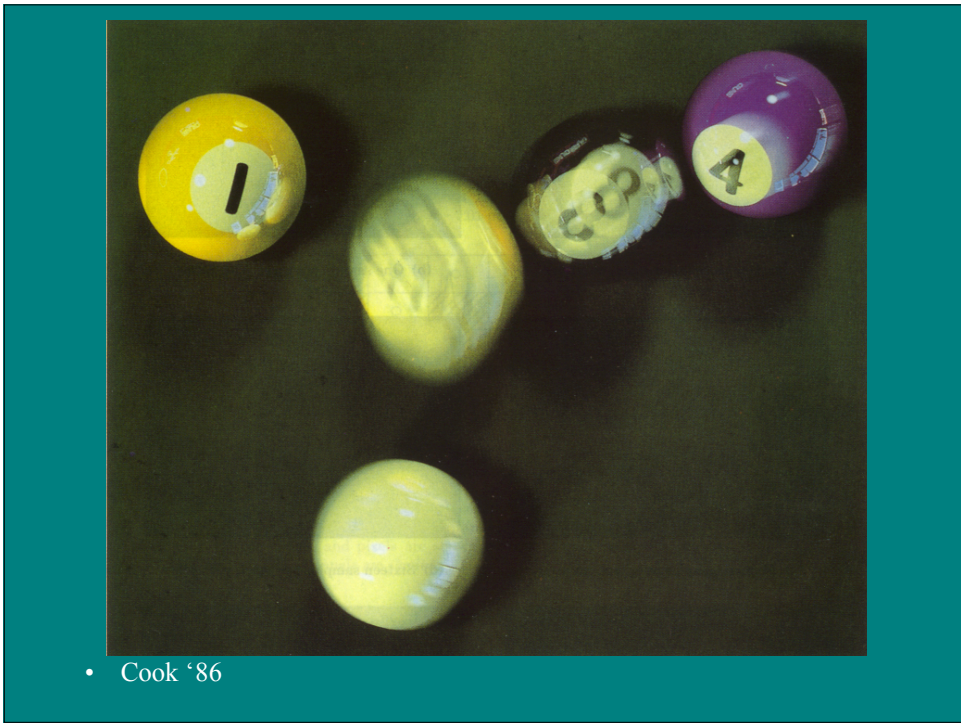
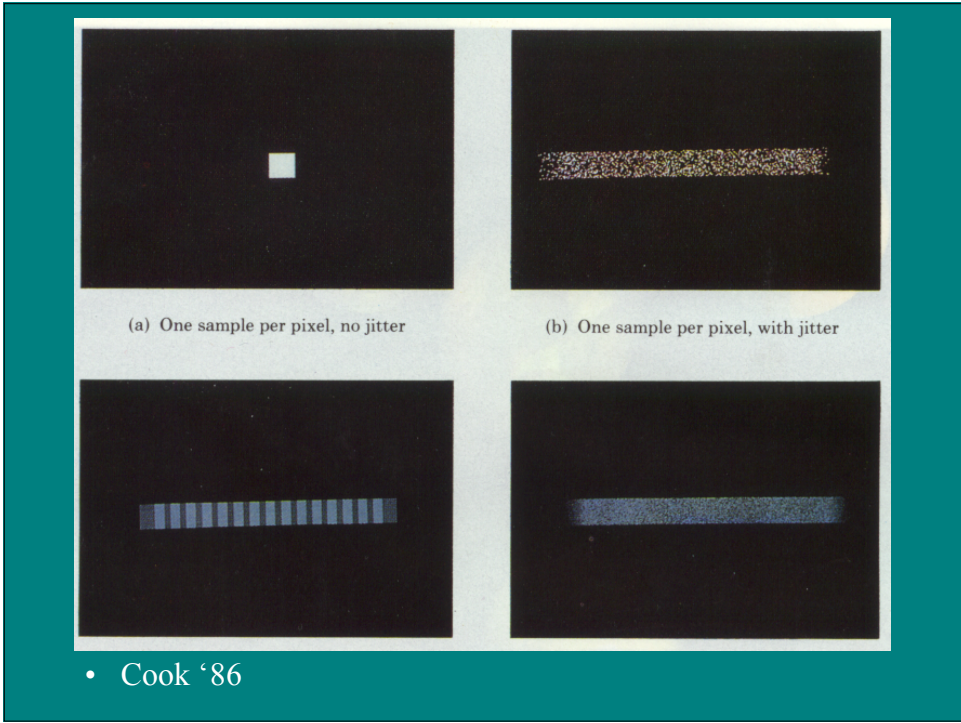
Figure 9. Anisotropic Artifacts

Preventing Aliasing

- Sufficient sampling rate/scheme
 - Determined by Nyquist limit
 - Non-regular sampling as substitute
- Appropriate reconstruction filter
 - Good lowpass filter
 - Reduce leakage of high frequencies

Other Stochastic Effects

- Motion blurring
- Depth of Field
- Gloss





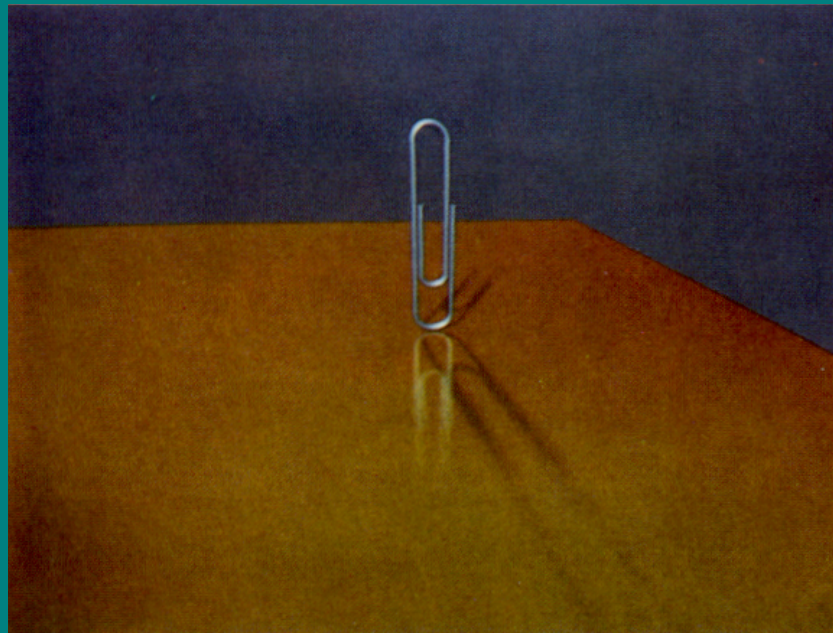
- Cook '86



- Cook '86



• Cook '86



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