

CMSC 471

Fall 2012

Class #7

Thu 9/20/12
Constraint Satisfaction

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Constraint Satisfaction

Chapter 6

Today's Class

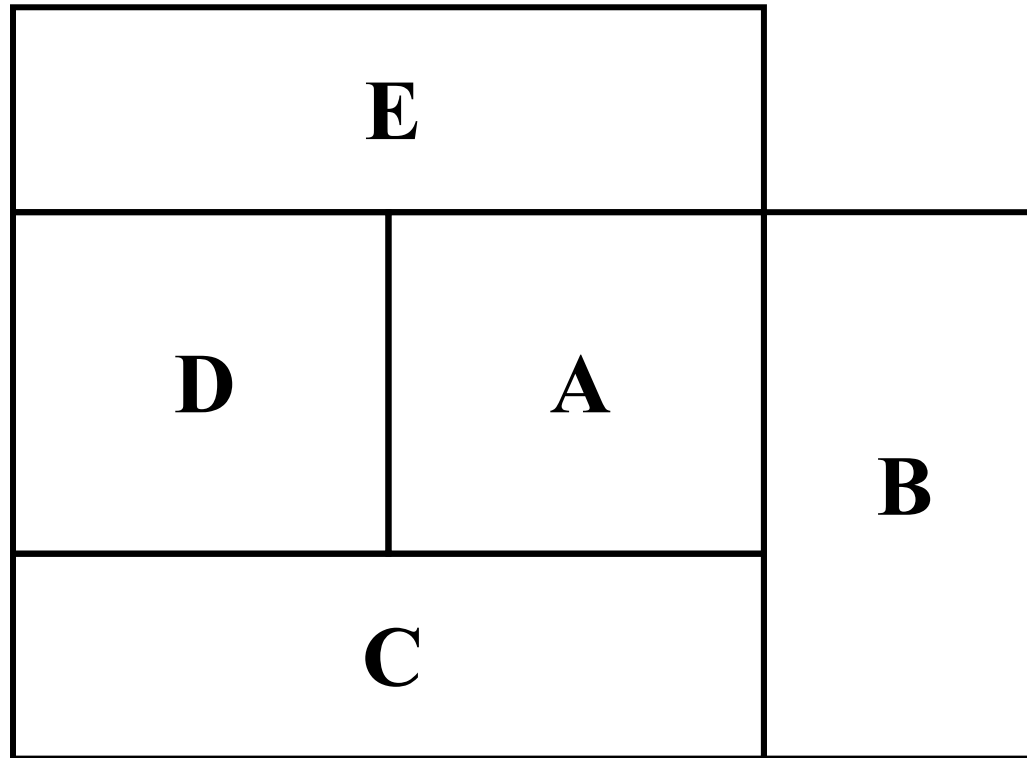
- Constraint Processing / Constraint Satisfaction Problem (CSP) paradigm
- Consistency
- Algorithms for CSPs
 - Backtracking (systematic search)
 - Constraint propagation (k-consistency)
 - Variable and value ordering heuristics
- HW2 rush-hour_basics.lisp

Overview

- Constraint satisfaction offers a powerful problem-solving paradigm
 - View a problem as a **set of variables** to which we have to assign **values** that satisfy a number of **problem-specific constraints**.
 - A **solution** to a CSP is then to find a set of **assignments** of a value to each variable which satisfies all of the constraints

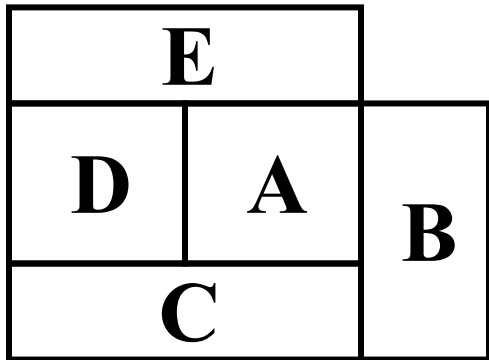
Informal Example: Map Coloring

- Color the following map using three colors (red, green, blue) such that no two adjacent regions have the same color.



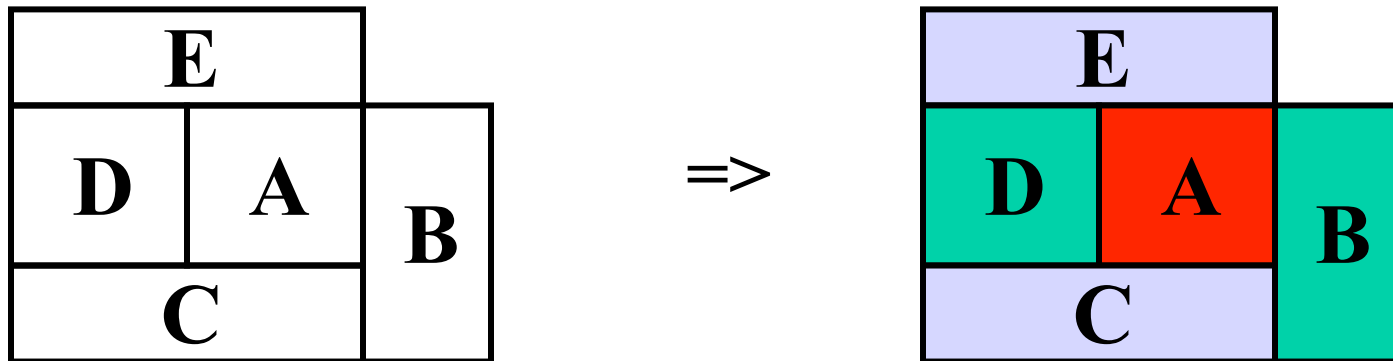
Map Coloring II

- Variables: A, B, C, D, E all of domain RGB
- Domains: $RGB = \{\text{red, green, blue}\}$
- Constraints: $A \neq B, A \neq C, A \neq E, A \neq D, B \neq C, C \neq D, D \neq E$
- One solution: A=red, B=green, C=blue, D=green, E=blue



Map Coloring II

- Variables: A, B, C, D, E all of domain RGB
- Domains: $RGB = \{\text{red, green, blue}\}$
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Formal Definition of a Constraint Network (CN)

A constraint network (CN) consists of

- a set of variables $X = \{x_1, x_2, \dots, x_n\}$
 - each with an associated domain of values $\{d_1, d_2, \dots, d_n\}$.
 - the domains are typically finite
- a set of constraints $\{c_1, c_2, \dots, c_m\}$ where
 - each constraint defines a predicate which is a relation over a particular subset of X .
 - e.g., C_i involves variables $\{X_{i1}, X_{i2}, \dots, X_{ik}\}$ and defines the relation $R_i \subseteq D_{i1} \times D_{i2} \times \dots \times D_{ik}$
- **Unary** constraint: only involves one variable
- **Binary** constraint: only involves two variables

Formal Definition of a CN (cont.)

- Instantiations
 - An **instantiation** of a subset of variables S is an assignment of a value in its domain to each variable in S
 - An instantiation is **legal** iff it does not violate any constraints.
- A **solution** is a legal instantiation of all of the variables in the network.

Typical Tasks for CSP

- Solutions:
 - Does a solution exist?
 - Find one solution
 - Find all solutions

Binary CSP

- A **binary CSP** is a CSP in which all of the constraints are binary or unary.
- A binary CSP can be represented as a **constraint graph**, which has a node for each variable and an arc between two nodes if and only there is a constraint involving the two variables.
 - Unary constraint appears as a self-referential arc

Example: Sudoku

| | | | |
|---|---|---|---|
| | 3 | | 1 |
| | 1 | | 4 |
| 3 | 4 | 1 | 2 |
| | | 4 | |

Running Example: Sudoku

- Variables and their domains
 - v_{ij} is the value in the j th cell of the i th row
 - $D_{ij} = D = \{1, 2, 3, 4\}$

- Blocks:
 - $B_1 = \{11, 12, 21, 22\}$
 - ...
 - $B_4 = \{33, 34, 43, 44\}$

- Constraints (implicit/intensional)
 - $C^R : \forall i, \cup_j v_{ij} = D$ (every value appears in every row)
 - $C^C : \forall j, \cup_i v_{ij} = D$ (every value appears in every column)
 - $C^B : \forall k, \cup (v_{ij} \mid ij \in B_k) = D$ (every value appears in every block)
 - Alternative representation: pairwise inequality constraints:
 - $I^R : \forall i, j \neq j' : v_{ij} \neq v_{ij'}$ (no value appears twice in any row)
 - $I^C : \forall j, i \neq i' : v_{ij} \neq v_{i'j}$ (no value appears twice in any column)
 - $I^B : \forall k, ij \in B_k, i'j' \in B_k, ij \neq i'j' : v_{ij} \neq v_{i'j'}$ (no value appears twice in any block)
 - Advantage of the second representation: all binary constraints!

| | | | |
|----------|----------|----------|----------|
| v_{11} | 3 | v_{13} | 1 |
| v_{21} | 1 | v_{23} | 4 |
| 3 | 4 | 1 | 2 |
| v_{41} | v_{42} | 4 | v_{44} |

Sudoku Constraint Network

Sudoku Constraint Network

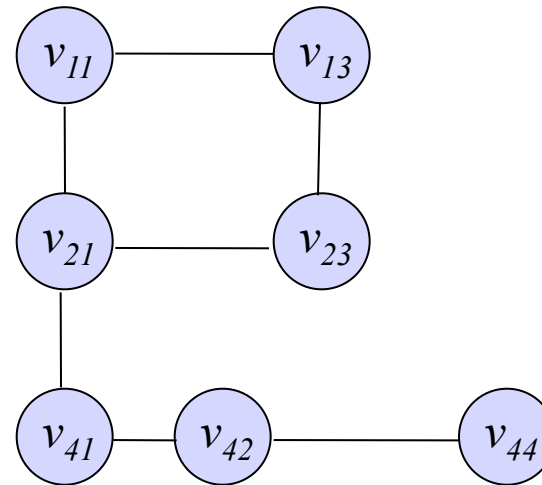
| | | | |
|---|---|---|---|
| | 3 | | 1 |
| | 1 | | 4 |
| 3 | 4 | 1 | 2 |
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Sudoku Constraint Network

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Sudoku Constraint Network

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Consistency

- Node consistency
 - A node X is **node-consistent** if every value in the domain of X is consistent with X 's unary constraints
 - A graph is node-consistent if all nodes are node-consistent
- Arc consistency
 - An arc (X, Y) is **arc-consistent** if, for every value x of X , there is a value y for Y that satisfies the constraint represented by the arc.
 - A graph is arc-consistent if all arcs are arc-consistent.
- To create arc consistency, we perform **constraint propagation**: that is, we repeatedly reduce the domain of each variable to be consistent with its arcs

K-consistency

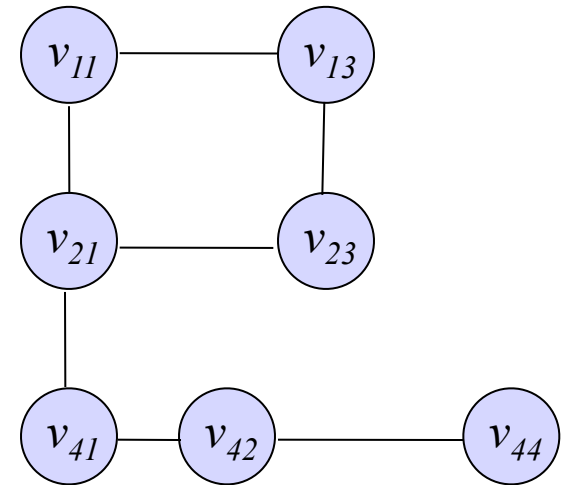
- K-consistency generalizes the notion of arc consistency to sets of more than two variables.
 - A graph is K-consistent if, for legal values of any K-1 variables in the graph, and for any Kth variable V_k , there is a legal value for V_k
- Strong K-consistency = J-consistency for all $J \leq K$
- **Node consistency = strong 1-consistency**
- **Arc consistency = strong 2-consistency**
- **Path consistency = strong 3-consistency**

Constraint Propagation: Sudoku

| | | | |
|----------|----------|----------|----------|
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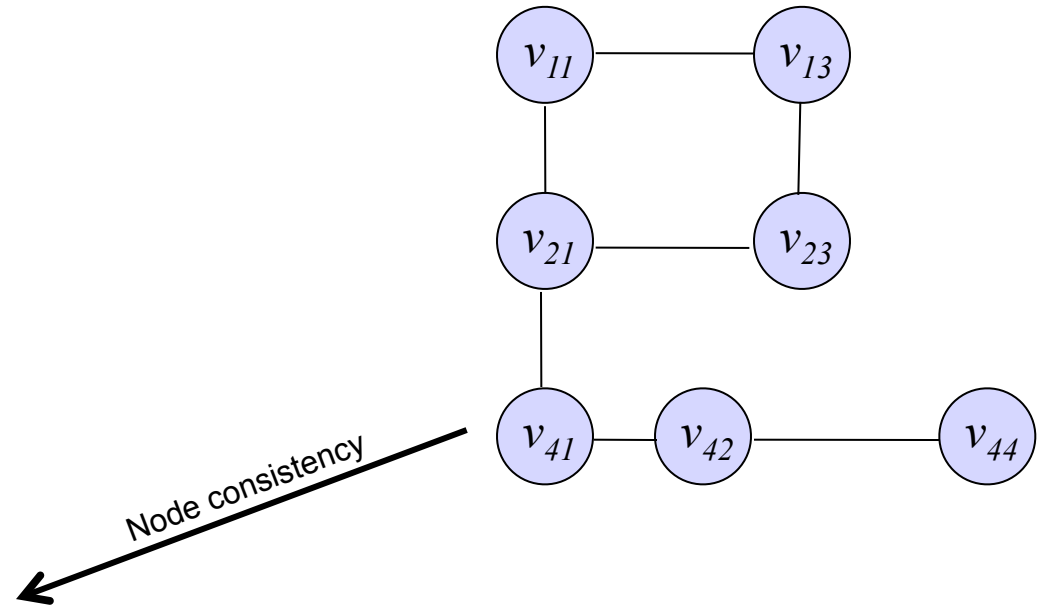
Constraint Propagation: Sudoku

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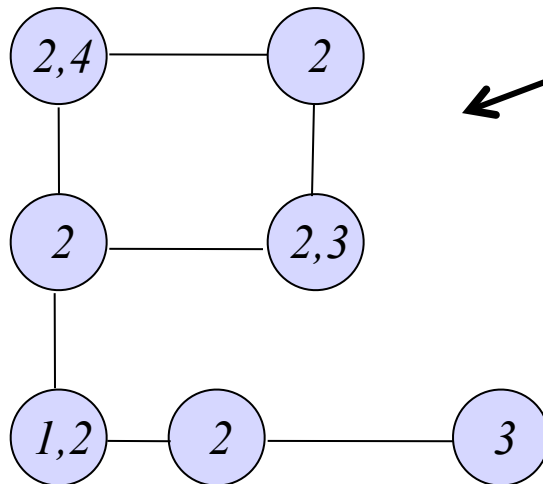
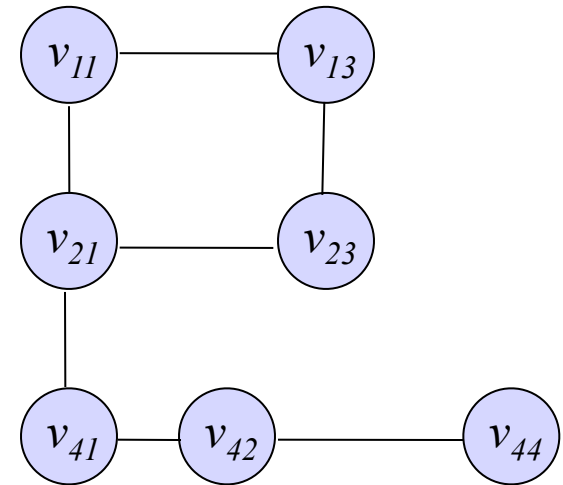
Constraint Propagation: Sudoku

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Constraint Propagation: Sudoku

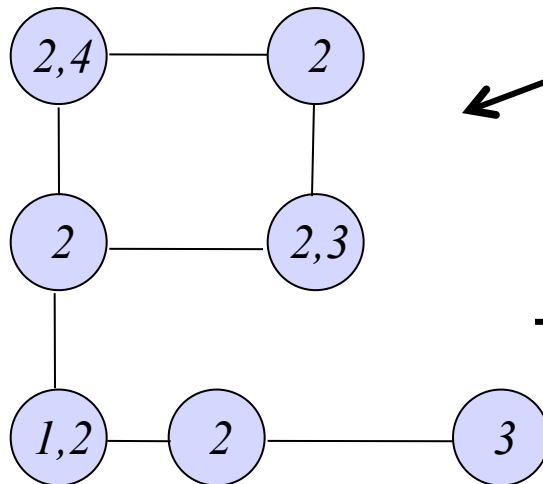
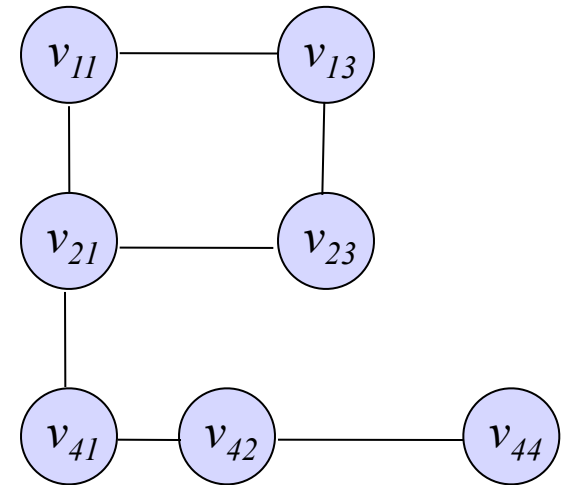
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Node consistency

Constraint Propagation: Sudoku

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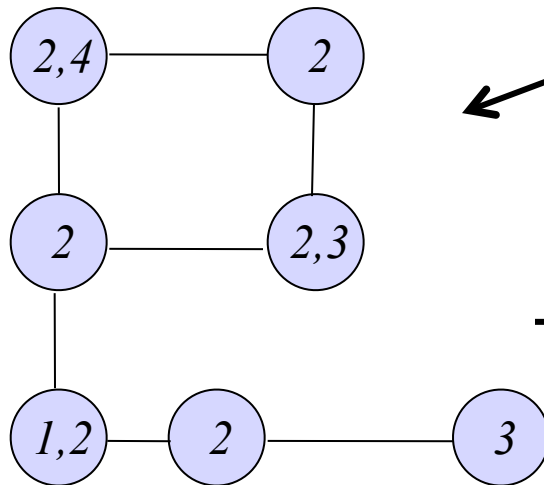


Node consistency

Arc consistency

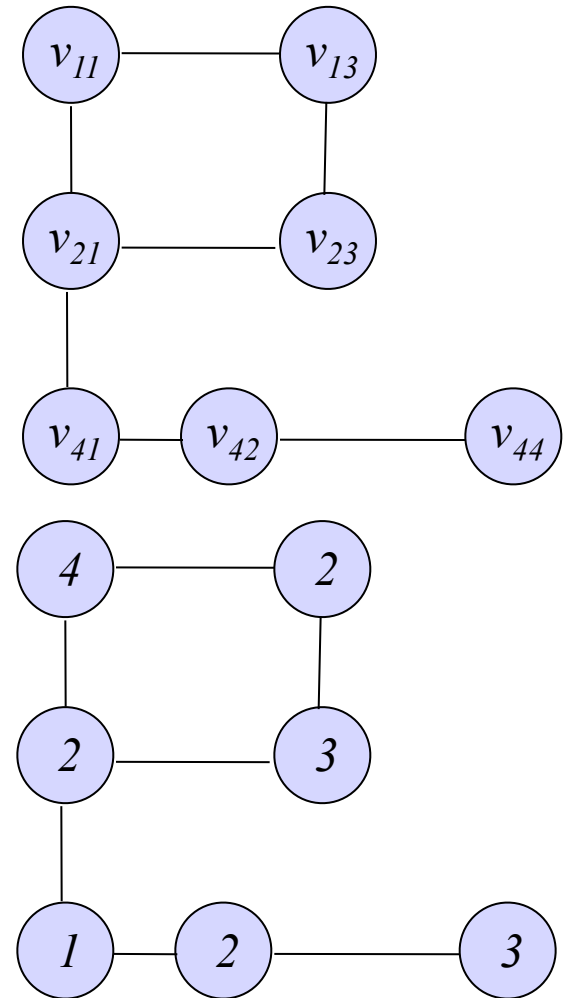
Constraint Propagation: Sudoku

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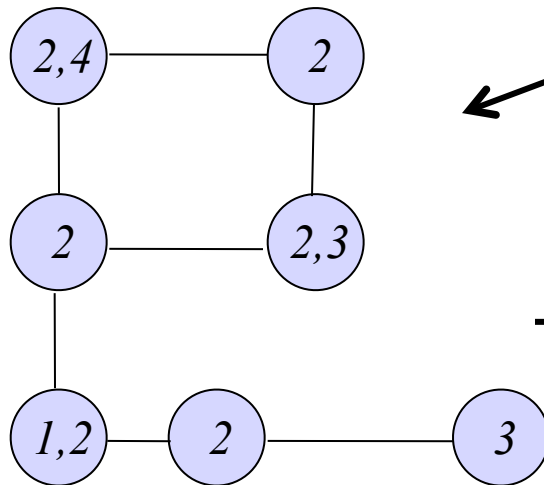
Node consistency

Arc consistency



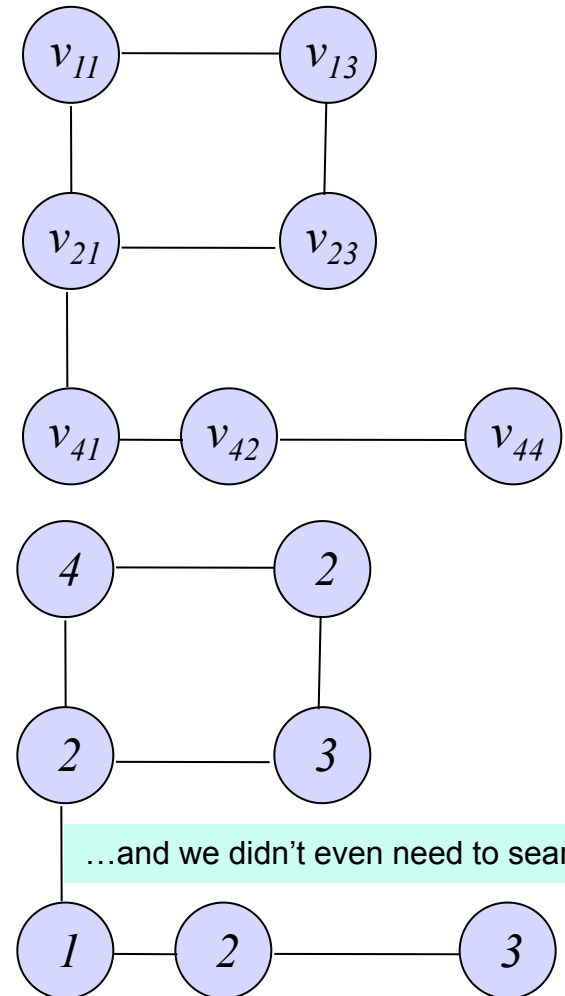
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Node consistency

Arc consistency



Solving Constraint Problems

- Systematic search
 - Generate and test
 - Backtracking
- Constraint propagation (consistency)
- Variable ordering heuristics
- Value ordering heuristics

Generate and Test: Sudoku

- Try each possible combination until you find one that works:

| | | | |
|----------|----------|----------|----------|
| <i>1</i> | 3 | <i>1</i> | 1 |
| <i>1</i> | 1 | <i>1</i> | 4 |
| 3 | 4 | 1 | 2 |
| <i>1</i> | <i>1</i> | 4 | <i>1</i> |

| | | | |
|----------|----------|----------|----------|
| <i>1</i> | 3 | <i>1</i> | 1 |
| <i>1</i> | 1 | <i>1</i> | 4 |
| 3 | 4 | 1 | 2 |
| <i>1</i> | <i>1</i> | 4 | <i>2</i> |

| | | | |
|----------|----------|----------|----------|
| <i>1</i> | 3 | <i>1</i> | 1 |
| <i>1</i> | 1 | <i>1</i> | 4 |
| 3 | 4 | 1 | 2 |
| <i>1</i> | <i>1</i> | 4 | <i>3</i> |

.....

- Doesn't check constraints until all variables have been instantiated
- Very inefficient way to explore the space of possibilities (4^7 for this trivial Sudoku puzzle, most illegal)

Systematic Search: Backtracking

(a.k.a. depth-first search!)

- Consider the variables in some order
- Pick an unassigned variable and give it a provisional value such that it is consistent with all of the constraints
- If no such assignment can be made, we've reached a dead end and need to backtrack to the previous variable
- Continue this process until a solution is found or we backtrack to the initial variable and have exhausted all possible values

Backtracking: Sudoku

Let's try it...

Backtracking: Sudoku

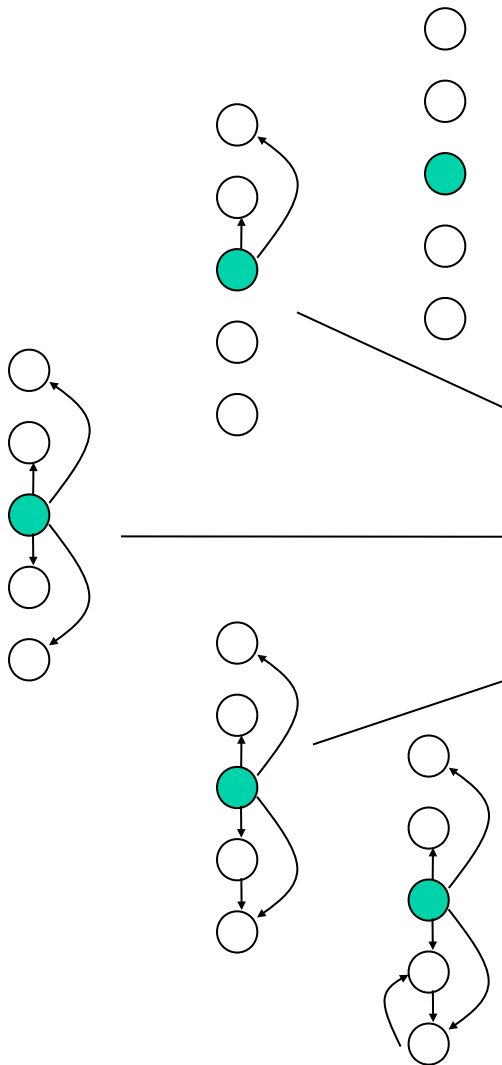
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Problems with Backtracking

- Thrashing: keep repeating the same failed variable assignments
 - Consistency checking can help
 - Intelligent backtracking schemes can also help
- Inefficiency: can explore areas of the search space that aren't likely to succeed
 - Variable ordering can help

Interleaving Constraint Propagation and Search



| | |
|---------------------|---|
| Generate and Test | No constraint propagation: assign all variable values, then test constraints |
| Simple Backtracking | Check constraints only for variables “up the tree” |
| Forward Checking | Check constraints for immediate neighbors “down the tree” |
| Partial Lookahead | Propagate constraints forward “down the tree” |
| Full Lookahead | Ensure complete arc consistency after each instantiation (AC-3) |

Variable Ordering

- As defined, Backtracking Search selects variables to instantiate *randomly*
- **Intuition**: choose variables that are highly constrained early in the search process; leave easy ones for later

Variable Ordering

- **Fail first principle** (FFP): choose variable with the fewest values (a.k.a. **minimum remaining values** (MRV))
 - **Static** FFP: use domain size of variables
 - **Dynamic** FFP (**search rearrangement method**): At each point in the search, select the variable with the fewest remaining values
- **Maximum cardinality ordering**: order variables by decreasing cardinality

Value Ordering

- **Intuition:** Choose values that are the least constrained early on, leaving the most legal values in later variables

Value Ordering

- **Maximal options method** (a.k.a. **least-constraining-value** heuristic): Choose the value that leaves the most legal values in uninstantiated variables
- **Min-conflicts**: Used in iterative repair search (see below)

Iterative Repair

- Start with an initial complete (but invalid) assignment
- Hill climbing, simulated annealing
- Min-conflicts: Select new values that minimally conflict with the other variables
 - Use in conjunction with hill climbing or simulated annealing or...
- Local maxima strategies
 - Random restart
 - Random walk
 - Tabu search: don't try recently attempted values

Min-Conflicts Heuristic

- Iterative repair method
 1. Find some “reasonably good” initial solution
 - E.g., in N-queens problem, use greedy search through rows, putting each queen where it conflicts with the smallest number of previously placed queens, breaking ties *randomly*
 2. Find a variable in conflict (randomly)
 3. Select a new value that minimizes the number of constraint violations
 - $O(N)$ time and space
 4. Repeat steps 2 and 3 until done
- Performance depends on quality and informativeness of initial assignment; inversely related to distance to solution