# XSB <br> TJss fijus <br> University of Maryland Baltimore County 

## Overview

What XSB offers
-Tabling
Higher order logic programming sort of
Negation

## What XSB Offers

LP languages have been based on SLDNF (SLD resolution with negation as failure) and implemented with the WAM (Warren Abstract Machine) model.
These suffer from some drawbacks: they address either positive or negative loops.
Positive loops result from recursion without negation.

- It has been addressed with magic sets and tabling, which assign failing values to derivation paths which contain positive loops.
$\Delta$ Negative Joops result from recursion through negation.
derivations are assigned the value undefined by well founded semantics.
XSB attempts to handle both and do so with efficiency approaching that of standard SLDNF as implemented, for example, by Prolog.

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## SLD-resolution rule

$<-A 1, \ldots, A(i-1), A i, A(I+1), \ldots, A m \quad B 0<-B 1, \ldots, B n$
$<-(A 1, \ldots, A(i-1), B 1, \ldots, B n, A(i+1), \ldots, A m) \sigma$
where

- A1, ..., Am are atomic formulas (goals)
- $\mathrm{B} 0<-\mathrm{B} 1, \ldots, \mathrm{Bn}$ is a (renamed) definite clause in $P$
- $\operatorname{mgu}(\mathrm{Ai}, \mathrm{BO})=\sigma$


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## Goal and clause selection

A goal selection function specifies which goal Ai is selected by the SLD-rule.

Prolog goes left-to-right
The order in which clauses are chosen is determined with a clause selection rule.

- Prolog selects clauses in the order in which they are added to the database

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## SLD-resolution is Sound and Complete for Horn Clauses

Any query (goal) that is provable with SLDresolution is a logical consequence of the program.
$\lrcorner$ Any query (goal) that is (true) in the least Herbrand model is provable with SLD-resolution.
In the case of an infinite SLD-tree, the selection function has to be fair (as in breadth first search). For finite SLD-trees left-first-with-backtracking as used in Prolog gives a complete method.

## SLD-tree

```
student of( (X,T) :- majors (X,C), teaches(T, C).
majors(paul, amsc).
majors(paul, ifsm).
majors(maria, m ath).
teaches (adrian, ifsm) .
teaches (peter, m ath).
teaches (peter, cmsc).
```


:-majors ( $\mathrm{S}, \mathrm{C}$ ), teaches (peter,C)


## Infinite SLD-tirees

```
brother(X, Y) :- brother(Y, X).
brother(paul, peter).
```


:-brother(peter, $Z$ ), brother $(Z, B)$

$\bullet$ brother (peter,adrian). brother (X, Y) :-
brother (X, Z) , brother (Z, Y) .

## Positive Loops in Prolog

We might like to use rules with loops:
\% Logically: parent $(X, Y) \Leftrightarrow$ child $(X, Y)$.
parent( $X, Y$ ) :- child $(X, Y)$.
child $(X, Y)$ :- parent $(X, Y)$.
parent(adam,able).
child(cain,eve).
\% Logically: spouse $(X, Y) \Leftrightarrow$ spouse $(Y, X)$.
spouse $(X, Y)$ :- spouse $(Y, X)$.
spouse(adam,eve)

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## Positive Loops in Prolog

Sometimes we are forced to...
\% Loops because there are cycles in the owes graph
avoids(Source,Target) :- owes(Source,Target).
avoids(Source,Target) :-
owes(Source,Intermediate), avoids(Intermediate,Target).
owes(andy,bill).
owes(bill,carl).
owes(carl,bill).

## Non-looping Prolog version

```
avoids(X,Y) :- avoids(X,Y,[ ]).
avoids(X,Y,L) :- owes(X,Y), \+ member(Y,L).
avoids(X,Y,L) :-
    owes(X,Z),
    1+ member(Z,L),
    avoids(Z,Y,[Z|L]).
owes(andy,bill).
owes(bill,carl).
owes(carl,bill).
```

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## More problems

Even if we prevent loping or the graph contains no cycles, its structure may lead to exponential computations.


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## Non-looping XSB version

:- table avoids/2.
avoids(Source,Target) :- owes(Source,Target).
avoids(Source, Target) :-
owes(Source,Intermediate),
avoids(Intermediate, Target).
owes(andy,bill).
owes(bill, carl).
owes(carl,bill).

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## SLD resolution: Program Clause Resolution

Given a tree with a node labeled

$$
\mathrm{A}:-\mathrm{A} 1, \mathrm{~A} 2 \ldots \mathrm{~A},
$$

and a rule in the program of the form
H:-B1,B2...BK
and given that H and B1 match with matching variable assignment Theta, then add a new node as a child of this one and label it with
(A :- B1,...,Bk,A2...An)Theta
if it does not already have a child so labeled. Note that the matching variable assignment is applied to all the goals in the new label.


Tree for avoid(andy, Ya) goal server


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## Tree for avoid(bill, Ya) goal server



## Tree for avoids(carl, Ya) goal server




## SLG resolution rules

Program Clause Resolutions Given (1) a tree with a node labeled $A:-A 1, A 2$...An, which is either a server tree root node or $A 1$ is not tabled and (2) a rule H:B1,B2...BK where H and A1 match with substitution Theta, then add a new child node with label ( $A:-B 1, \ldots, B k, A 2$...An) Theta, if it does not already have a child so labeled.
Subgoal cally Given a nonroot node with label, where A1 is indicated as tabled, and there is no tree with root A1 :- A 1 , create a new tree with root A 1 :- A 1 .
$\lrcorner$ Answer Clause Resolution Given a non-root node with label $A:-A 1, A 2 \ldots$ An, and an answer of the form $B$ :in the tree for $A 1$, then add a new child node labeled by (A:-A2..An) Theta, where Theta is the substitution obtained from matching $B$ and $A 1$ (if there is not already a child with that label.)

## Left recursive version

The left-recursive version is, in fact, more efficient in XSB.
:- table avoids/2.
avoids(Source, Target) :- owes(Source, Target).
avoids(Source,Target) :-
avoids(Source,Intermediate),
owes(Intermediate, Target),
Only one table is generated by the query avoids(andy, Ya) instead of three.


## Hilog terms

XSB has a simple extension that provides some "higher-order" logic programming capability.
A term in XSB is:
-an atomic symbol, or

- a variable, or
of the form: to( $\left.\mathrm{t} 1, \mathrm{t}_{2}, \ldots, \mathrm{tn}\right)$ where the ti are terms.
$\Delta$ Transitive closure example:
closure $(R)(X, Y):-R(X, Y)$.
closure $(R)(X, Y):-R(X, Z)$, closure $(R)(Z, Y)$.
:- hilog parent.
ancestor $(X, Y)$ :- closure(parent $)(X, Y)$.
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## Some examples

```
map(F)([],[]).
map(F)([X|Xs],[Y|Ys]) :-
    F(X,Y),
    map(F)(Xs,Ys).
twice(F)(X,R) :-
    F(X,U),
    F(U,R).
:- hilog successor,double,square.
successor(X,Y) :- Y is X+1.
double(X,Y) :- Y is }X+X\mathrm{ .
square(X,Y) :- Y is }X*X
```

```
| ?- map(successor)([2,4,6,8],L).
L = [3,5,7,9]
| ?- map(double)([2,4,6,8,10],L).
L = [4,8,12,16,20];
| ?- twice(successor)(1,X).
X = 3
| ?- twice(twice(successor))(1,X).
X = 5
| ?- twice(twice(square))(2,X).
X = 65536
| ?- twice(twice(twice(double)))(1,X).
X = 256
```


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## How it's done

If $T$ is a variable or compound term or a hilog term, rewrite:

$$
\mathrm{T}(\mathrm{~A} 1 . . . \mathrm{A} \mathrm{n}) \rightarrow \operatorname{apply}(\mathrm{T}, \mathrm{~A} 1, \ldots \mathrm{~A} \mathrm{n})
$$

So the clauses:

```
closure(R)(X,Y) :- R(X,Y).
```

closure $(R)(X, Y)$ :- $R(X, Z)$, closure $(R)(Z, Y)$.
ancestor $(X, Y)$ :- closure(parent) $(X, Y)$.
parent(adam,cain). parent(cain,enoch)

Become:
apply(closure $(R), X, Y)$ :- apply $(R, X, Y)$.
apply(closure $(R), X, Y)$ :- apply $(R, X, Z)$, apply(closure $(R), Z, Y)$.
ancestor $(X, Y)$ :- apply(parent, $X, Y$ ).
apply(parent,adam,cain). apply(parent,cain,enoch).
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## Negation in XSB

$1++P$, fail_if $(+P)$, not $(+P)$ are all like Prolog's $\mid++P$ : $\operatorname{not}(P):-\operatorname{call}(P)$, !, fail not(_).
-tnot(P) is Xsb's negation operator and allows for the correct execution of programs with well founded semantics.
-P must be a tabled predicate,

## Negation

```
bachelor(X):-
    male(X),
    I+ married(X).
    male(bill),
    male(jim),
    married(bill).
married(mary),
```

```
?- bachelor(bill).
no
| ?- bachelor(jim).
yes
| ?- bachelor(mary).
no
| ?- bachelor(X).
X = jim;
No
```

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## Floundering goals

$\rightarrow$ Prolog treats $\backslash+$ as negation as failure which is sound if we make the closed world assumption
To guarantee reasonable answers, the negation operator should be applied only to ground Ifterals.
$\lrcorner$ If 'it is applied to a nonground literal, the program is said to flounder.
Some LP languages define not like

$$
\text { not }(P) \text { :- ground }(P)->(1+P) \mid \operatorname{error}\left({ }^{\prime \prime} \ldots{ }^{\prime \prime}\right) \text {. }
$$

## Floundering goal

    bachelor \((x)\) :-
    \(1+\) married \((X)\),
    male( \(X\) ),
    male(bill),
male(jim).
married(bill).
married(mary).
?- bachelor(bill).
no
| ?- bachelor(jim).

```
yes
```

| ?- bachelor(mary).
no
| ?- bachelor(X).
no
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## Stratified Negation

- A program is stratified if there are no cycles in the call graph which contain a call to P and to not(P).
i.e., no recursion
through negation
- XSB allows nonstratified programs to be evaluated.
\% A set is normal if it doesn't
\% contain itself normal(S) :- $1+\mathrm{in}(S, S)$
$\%$ mySet is the set of all sets
\% that are normal.
in(S,mySet) :- normal(S).
\% is mySet normal?
?- normal(myset)
\% this leads to Russell's paradox
\% and will cause Prolog to loop


## Stratified Negation

## a $-b-a-c$ <br> (i) $=$ b $-(f)=g-k$

 operator and want to apply it to an object and want to repeatedly apply it until it can't be reduced any further.$\perp$ If there are cycles, treat the objects in the cycle (the strongly connected components or SCCs) as equivalently reduced.

```
:- table reachable/2.
reachable(X,Y) :- reduce(X,Y).
reachable(X,Y) :-
    reachable(X,Z),
    reduce(Z,Y).
```

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```
reduce(a,b).
reduce(b,c).
reduce(c,d).
reduce(d,e).
reduce(e,c).
reduce(a,f).
reduce(f,g).
reduce(g,f).
reduce(g,k).
reduce(f,h).
reduce(h,i).
reduce(i,h).
```


## Stratified Negation

- A node is reducible if it can be further reduced.
- A node $X$ can be fully reduced to another $Y$ if $X$ can be reduced to $Y$ and $Y$ is not further reducible.

```
:- table reducible/1.
reducible(X) :-
    reachable(X,Y),
    tnot(reachable(Y,X)).
fullyReduce(X,Y) :-
    reachable(X,Y),
    tnot(reducible(Y)).
```


reduce $(\mathrm{a}, \mathrm{b})$.
reduce(b,c).
reduce(c,d).
reduce(d,e).
reduce(e,c).
reduce (a,f).
reduce( $\mathrm{f}, \mathrm{g}$ ).
reduce $(\mathrm{g}, \mathrm{f})$.
reduce(g,k).
reduce(f,h).
reduce(h,i).
reduce(i,h).

## Stratified Negation

- We might want to return a representative object from a SCC.
- We'll pick (arbitrarily) the smallest.
fullyReduceRep(X,Y) :fullyReduce(X,Y), tnot(smallerequiv(Y)).
smallerequiv $(\mathrm{X})$ :reachable( $\mathrm{X}, \mathrm{Y}$ ), Y@<X, reachable(Y,X).


## $a \rightarrow b-c-d-a$ <br> $i \Rightarrow h \rightarrow f \Rightarrow g$

```
| ?- fu|lyReduce(a,X)
```

| ?- fu|lyReduce(a,X)
X= c;
X= c;
X = h;
X = h;
X = d;
X = d;
x=k;
x=k;
X = i;
X = i;
x = e;
x = e;
No
No
| ?- fullyReduceRep(a,X).
| ?- fullyReduceRep(a,X).
X = c;
X = c;
x=h;
x=h;
x=k;
x=k;
no

```
no
```

This is a Stratified Program

- There is no recursion thru negation.
- We can safely do the computation if we work from the bottom up.


## fullyReduce


reduce

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## Stratified or not?

-This simple program, when
executed, does not recurse
thru negation.
-S can be proven (by XSB)
even tho Prolog would loop.
-If we change the order of
the literals in the clauses for
$\mathrm{p}, \mathrm{q}$ and r ?


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## Well-founded semantics of non-stratified negation.

XSB handles non-stratified programs computing answers using "well founded semantics"
In WFS there are three truth values: true, false and unknown
Atoms that depend on themselves negatively are assigned the value unknown.

- Example:

The barber shaves everyone who does not shave himself.

- shaves $($ barber, $X$ ) :- tnot $(\operatorname{shaves}(X, X))$


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## example



